

Thermal Segmentation of Mid-Ocean Ridge Transform Faults

Monica Wolfson-Schwehr^{1*}, Margaret S. Boettcher^{1†}, Mark D. Behn²

¹Department of Earth Sciences, University of New Hampshire, Durham, NH, USA, ²Department of Geology and Geophysics, Woods Hole Oceanographic Institute, Woods Hole, MA, USA

*Now at Monterey Bay Aquarium Research Institute, Moss Landing, CA, USA

†Currently at School of Earth and Environment, University of Western Australia, Perth, Western Australia, Australia

Contents of this file

Figures S1

Introduction

The equation for A_U , the seismogenic area for an unsegmented mid-ocean ridge transform fault (Eq. 7 in the paper):

$$A_U = C_{600} L_T^{1.5} V^{-0.5}$$

and the equation for L_S , the critical step-over length (Eq. 11 in the paper):

$$\widetilde{L}_S = C_0 \frac{L_1^{1.5} + L_2^{1.5} - 0.1|L_1 - L_2|^{1.5}}{L_1 + L_2} V^{-0.6}$$

have the same exponent on the length terms (L_T , L_1 and L_2), but different exponents on the slip rate (V). In order to show the significance of the exponent on the slip rate (V_{exp}) for A_U and \widetilde{L}_S , we plot a range of exponent values versus the computed percent error between A_U and \widetilde{L}_S derived from the model, and A_U and \widetilde{L}_S predicted from the scaling

relation with the given exponent value for the full range of slip rates (2 cm/yr to 14 cm/yr) for a segmented fault system composed of two 50-km long faults (Fig. S1). In figure S1, panel (a) shows the V_{exp} versus percent error plot for A_U and panel (b) shows the same plot for \widetilde{L}_S . In the case of the scaling relation for A_U , the percent error is minimized at a V_{exp} value of -0.46 for all slip rates. In the case of the scaling relation for \widetilde{L}_S , the percent error is minimized at different V_{exp} values depending on the slip rate. The spread in the percent error values, however, is minimized for a value of -0.59. The V_{exp} exponent values are then rounded to two significant digits (-0.5 and -0.6, respectively) for use in the A_U and \widetilde{L}_S equations. The use of a V_{exp} value of -0.5 in the equation for A_U matches the theoretical value derived from the halfspace cooling model [Boettcher & Jordan, 2004]. Rounding this term results in a negligible increase the percent error for both A_U and \widetilde{L}_S .

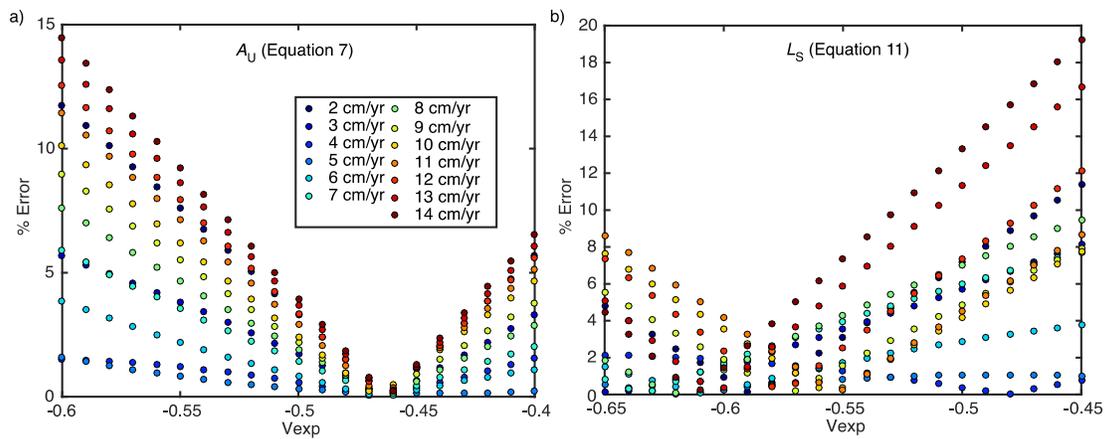


Figure S1. Percent error versus the exponent on the slip rate term (V) in the equations for A_U (a) and \widetilde{L}_S (b) for a segmented fault composed of two 50-km long fault segments. Data points are colored by slip rate.

For each value of the slip rate exponent tested in the scaling relations in figure S1, a new constant is computed, C_{600} for A_U and C_0 for \widetilde{L}_S . In the equation for A_U , a V_{exp} value of -0.5 corresponds to a C_{600} value of $6.87e-4$ (m/s) $^{(1/2)}$. For \widetilde{L}_S with a V_{exp} value of -0.6, $C_0 = 1.35e-4$ m $^{1.1} s^{-0.6}$. We round these numbers to two significant digits as well ($6.9e-4$ and $1.4e-4$, respectively) to simply the equations and preserve consistency in the significant digits.