Stress, Salt Flux, and Dynamics of a Partially Mixed Estuary

by


August 1998

Technical Report

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Stress, Salt Flux, and Dynamics of a Partially Mixed Estuary

by

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TABLE OF CONTENTS

LIST OF FIGURES ................................................................................................................ ii
LIST OF TABLES ....................................................................................................................... iv
I. INTRODUCTION ..................................................................................................................... 1
II. INSTRUMENTATION ............................................................................................................. 5
III. DEPLOYMENT & SAMPLING SCHEMES ........................................................................... 15
IV. DATA PROCESSING ............................................................................................................ 23
V. DATA SUMMARIES ............................................................................................................. 29
VI. FILE DESCRIPTIONS ......................................................................................................... 119
VII. ACKNOWLEDGEMENTS ................................................................................................. 127
VIII. REFERENCES .................................................................................................................. 131
# LIST OF FIGURES

**Figure 1.** Site Map ................................................................................................................. 3

**SCHEMATICS**
- **Figure 2.** Schematic of Quadrapod ............................................................................... 9
- **Figure 3.** Schematic of Tripods with E & F Moorings .................................................. 11
- **Figure 4.** Schematic of Central Moorings ...................................................................... 12
- **Figure 5.** USGS NOS Bathymetry .................................................................................. 16
- **Figure 6.** Transect Bottom Profiles with Cross-Channel Positions .............................. 18

**QUADRAPOD TIMESERIES**
- **Figure 7.** Salinity & Temperature (Deployment I) .................................................... 32
- **Figure 8.** Pressure & OBS (Deployment I) ................................................................. 33
- **Figure 9.** Horizontal Velocity (Deployment I) ............................................................. 34
- **Figure 10.** Salinity & Temperature (Deployment II) ...................................................... 35
- **Figure 11.** Pressure & OBS (Deployment II) ............................................................... 36
- **Figure 12.** Horizontal Velocity (Deployment II) .......................................................... 37

**TRIPOD & MOORING TIMESERIES**
- **Figure 13.** Tripod A: Salinity & Temperature .......................................................... 40
- **Figure 14.** Tripod A: Pressure ..................................................................................... 41
- **Figure 15.** Tripod B: Salinity & Temperature ............................................................... 42
- **Figure 16.** Tripod B: Pressure ...................................................................................... 43
- **Figure 17.** Central Mooring: Temperature .................................................................. 44
- **Figure 18.** Central Mooring: Salinity ........................................................................ 45
- **Figure 19.** Central Mooring: Pressure ......................................................................... 46
- **Figure 20.** Central Mooring: Horizontal Velocity ....................................................... 47
- **Figure 21.** ADCP Tripod: Salinity & Temperature ...................................................... 48
- **Figure 22.** ADCP Tripod: Pressure ............................................................................. 49
- **Figure 23.** ADCP Tripod: Along-Channel Velocity .................................................... 50
- **Figure 24.** ADCP Tripod: Cross-Channel Velocity ...................................................... 51
- **Figure 25.** Tripod D: Salinity & Temperature .............................................................. 52
- **Figure 26.** Tripod D: Pressure .................................................................................... 53
- **Figure 27.** Tripod D: Horizontal Velocity ..................................................................... 54
- **Figure 28.** Mooring E: Salinity & Temperature .......................................................... 55
- **Figure 29.** Tripod E: Salinity & Temperature ............................................................... 56
- **Figure 30.** Tripod E: Horizontal Velocity ...................................................................... 57
- **Figure 31.** Mooring F: Salinity & Temperature ........................................................... 58
- **Figure 32.** Tripod F: Salinity & Temperature ............................................................... 59
- **Figure 33.** Tripod F: Pressure ..................................................................................... 60
- **Figure 34.** Tripod F: Horizontal Velocity ..................................................................... 61
- **Figure 35.** Shipboard Sidescan Survey (summary) ...................................................... 62

**SHIPBOARD LONGITUDINAL SURVEYS**
- **Figure 36.** Salinity & Temperature Contours (8/17/95) ............................................. 64
- **Figure 37.** Salinity & Temperature Contours (8/27/95) ............................................. 66
- **Figure 38.** Salinity & Temperature Contours (10/18/95) ........................................... 68
- **Figure 39.** Salinity & Temperature Contours (10/20/95) ........................................... 70
- **Figure 40.** Salinity & Temperature Contours (10/22/95) ........................................... 72

(... continued on next page)
LIST OF FIGURES (continued)

SHIPBOARD TRANSECT SURVEYS
Figure 41. South Transect: Salinity & Velocity Contours (8/18/95) .................................... 74
Figure 42. Middle Transect: Salinity & Velocity Contours (8/18/95) .................................... 76
Figure 43. North Transect: Salinity & Velocity Contours (8/18/95) .................................... 78
Figure 44. South Transect: Salinity & Velocity Contours (8/28/95) .................................... 80
Figure 45. Middle Transect: Salinity & Velocity Contours (8/28/95) .................................... 82
Figure 46. North Transect: Salinity & Velocity Contours (8/28/95) .................................... 84
Figure 47. South Transect: Salinity & Velocity Contours (10/19/95) .................................... 86
Figure 48. Middle Transect: Salinity & Velocity Contours (10/19/95) .................................... 88
Figure 49. North Transect: Salinity & Velocity Contours (10/19/95) .................................... 90
Figure 50. South Transect: Salinity & Velocity Contours (10/21/95) .................................... 92
Figure 51. Middle Transect: Salinity & Velocity Contours (10/21/95) .................................... 94
Figure 52. North Transect: Salinity & Velocity Contours (10/21/95) .................................... 96
Figure 53. South Transect: Salinity & Velocity Contours (10/23/95) .................................... 98
Figure 54. Middle Transect: Salinity & Velocity Contours (10/23/95) .................................. 100
Figure 55. North Transect: Salinity & Velocity Contours (10/23/95) .................................. 102

SHIPBOARD LONG SURVEYS
Figure 56. Long Survey Tidal Summary ............................................................................. 104
Figure 57. Salinity & Temperature Contours (8/20/95) ......................................................... 105
Figure 58. Salinity & Temperature Contours (8/29/95) ......................................................... 106
Figure 59. Salinity & Temperature Contours (10/16/95) ....................................................... 107
Figure 60. Salinity & Temperature Contours (10/25/95) ....................................................... 108

SENSOR COMPARISONS
Figure 61. MET meteorological time series ......................................................................... 110

Figure 62. Pressure from ADCP Tripod with Quadrapod .................................................... 112
Figure 63. Horizontal Velocity from ADCP with BASS ....................................................... 114
Figure 64. Temperature & Salinity from ADCP Tripod with Quadrapod .......................... 116
Figure 65. Temperature & Salinity from ADCP Tripod with C-Mooring ......................... 116
Figure 66. NGBC Buoy Wind Velocity with 79th St. MET Station .................................... 117
LIST OF TABLES

Table 1. Quadrapod, Tripod & Mooring Instrumentation ..................................................... 7
Table 2. Summary of Deployments ...................................................................................... 17
Table 3. Summary of Shipboard Surveys .............................................................................. 20
Table 4. BASS Zeros .............................................................................................................. 25
SECTION I

INTRODUCTION
A field study was performed in the lower Hudson River, a partially mixed estuary with a relatively simple geometry (Figure 1), between August and October of 1995. The objectives of the study were (1) to quantify and characterize the turbulent transport of momentum and salt, and (2) to relate the turbulent transport processes to the local and estuary-wide dynamics.

The measurement program consisted of fixed and shipboard components. At a central site, a moored array of temperature-conductivity sensors and optical backscatter sensors (OBS), a bottom-mounted acoustic Doppler current profiler (ADCP), and a bottom-mounted array of acoustic travel-time current sensors (BASS), temperature-conductivity sensors, and OBS sensors resolved the vertical structure of velocity, salinity and turbidity and the near-bottom turbulence structure. Moored and bottom-mounted velocity, temperature, conductivity and pressure sensors at five secondary sites quantified the spatial and temporal variability of velocity, salinity and bottom pressure. Shipboard measurements with an ADCP and a conductivity-temperature-depth (CTD) profiler, accompanied by an OBS sensor, resolved the spatial structure and tidal variability of velocity, salinity and turbidity along several cross-channel and along-channel transects.

This report describes the measurements in detail. Section II describes the instrumentation, Section III describes the deployment and sampling schemes, Section IV describes the data processing, and Section V is a summary of plots of selected data. Section VI documents the data files and Sections VII and VIII give acknowledgments and references.

Figure 1.
SECTION II

INSTRUMENTATION
A. OVERVIEW

This section describes instrumentation developed for the experiment: a quadrapod, six 1-meter tripods, three moorings and the meteorological station, as well as the shipboard data collection system. The tripods and moorings are named A through F, which relate to the deployment sites, as described in Section III and shown in Figure 1.

Table 1. QUADRAPOD, TRIPOD & MOORING INSTRUMENTATION

<table>
<thead>
<tr>
<th>Inst ID: Site-Type</th>
<th>Height Above Bottom (mab)</th>
<th>Observed Property</th>
<th>Instrument (Model Number)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A-tripod</td>
<td>0.9</td>
<td>T C P V O</td>
<td>Seagauge/26-03 (SG46)</td>
</tr>
<tr>
<td>B-tripod</td>
<td>0.9</td>
<td>T C P V O</td>
<td>Seagauge/26-03 (SG41)</td>
</tr>
<tr>
<td>C-mooring</td>
<td>depth-2.7</td>
<td>T C P V O</td>
<td>Seacat (SBE 16-04)/C-1 (SC70) (OBS608)</td>
</tr>
<tr>
<td></td>
<td>depth-4.3</td>
<td>T C O</td>
<td>Seacat (SBE 16-04)/C-2 (SC71) (OBS611)</td>
</tr>
<tr>
<td></td>
<td>depth-6.3</td>
<td>T C O</td>
<td>Seacat (SBE 16-04)/C-3 (SC73) (OBS420)</td>
</tr>
<tr>
<td></td>
<td>depth-8.3</td>
<td>T C O</td>
<td>Seacat (SBE 16-04)/C-4 (SC72) (OBS424)</td>
</tr>
<tr>
<td></td>
<td>depth-10.3</td>
<td>T C O</td>
<td>Seacat (SBE 16-04)/C-5 (SC884)</td>
</tr>
<tr>
<td></td>
<td>depth-12.3</td>
<td>T C O</td>
<td>Seacat (SBE 16-04)/C-6 (SC885)</td>
</tr>
<tr>
<td>ADCP-trpod</td>
<td>0.9</td>
<td>T C P V</td>
<td>ADCP (SN 0387)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Seagauge/26-03 (SG45)(PS8202)</td>
</tr>
<tr>
<td>BASS-quadrapod</td>
<td>0.3</td>
<td>T C V O</td>
<td>Seabird-1 (041425) / BASS-1 / OBS-1</td>
</tr>
<tr>
<td></td>
<td>0.6</td>
<td>T C V O</td>
<td>Seabird-2 (031718)</td>
</tr>
<tr>
<td></td>
<td>1.2</td>
<td>T C V O</td>
<td>Seabird-3 (041482*) / BASS-2 / OBS-2</td>
</tr>
<tr>
<td></td>
<td>1.6</td>
<td>T C V O</td>
<td>Seabird-4 (041481) / BASS-3 / OBS-3</td>
</tr>
<tr>
<td></td>
<td>2.1</td>
<td>T C V O</td>
<td>Seabird-5 (031719)</td>
</tr>
<tr>
<td></td>
<td>2.9</td>
<td>T C V O</td>
<td>Seabird-6 (041462*) / BASS-4 / OBS-4</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Seabird-7 (031720)</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td>Seabird-8 (648) / BASS-5 / OBS-5</td>
</tr>
<tr>
<td>D-tripod</td>
<td>0.9</td>
<td>T C P V</td>
<td>Seagauge/26-03 (SG49)</td>
</tr>
<tr>
<td></td>
<td>1.1</td>
<td></td>
<td>S4 (04911003)</td>
</tr>
<tr>
<td>E-mooring</td>
<td>depth-1.0</td>
<td>T C O</td>
<td>Seacat (SBE 16-04) (SC68) (OBS409)</td>
</tr>
<tr>
<td>E-tripod</td>
<td>0.9</td>
<td>T C V O</td>
<td>Seacat (SBE 16-04) (SC883) (OBS410)</td>
</tr>
<tr>
<td></td>
<td>1.1</td>
<td></td>
<td>S4 (05191143)</td>
</tr>
<tr>
<td>F-mooring</td>
<td>depth-1.0</td>
<td>T C O</td>
<td>Seacat (SBE 16-04) (SC882) (OBS423)</td>
</tr>
<tr>
<td>F-tripod</td>
<td>0.9</td>
<td>T C P V</td>
<td>Seacat (SBE 16-04) (SC885)</td>
</tr>
<tr>
<td></td>
<td>1.1</td>
<td></td>
<td>S4 (18291515)</td>
</tr>
</tbody>
</table>

* Conductivity cells 041462 and 041482 labels had been switched before the first deployment. The labeling was corrected by Seabird Electronics during the September(1995) calibrations and are shown correctly above.
Figure 2a. Side and Top View of Quadrupod
Figure 2b. Front View of Quadrapod
B. QUADRAPOD

A quadrapod was constructed to support five BASS acoustic travel-time velocity sensors (Williams et al., 1987) in a vertical column. The structure also supported five Seabird conductivity sensors, three Seabird temperature sensors, five D & A optical backscatter sensors (OBS), a Digiquartz ParoScientific pressure sensor, a compass and a tiltmeter. (See Table 1 and Figure 2.)

BASS sensors measure differential travel-time of acoustic pulses, along four axes, to compute three dimensional velocity in a 15-cm sample volume. Absolute travel-time was also stored for Path C of each sensor to determine sound speed (Trivett 1991), which is related to salinity, temperature and depth (MacKenzie 1981). High noise levels in the absolute travel-time board prohibit use of the travel time data during the HUMIX experiment, but the measurements provided an opportunity to resolve critical issues for future development of travel time instrumentation.

The conductivity cells and OBSs were arranged on a channel 0.6 meters away from the BASS tower at the same heights as the BASS sensors and temperature sensors were placed on the same channel at the bottom, middle and top heights. The pressure sensor was approximately 1.7 meters away from the BASS tower, at 1.56 meters above bottom. Counters were used to sample these properties simultaneously (Williams 1995). Pressure cases containing batteries, sensor electronics and data acquisition systems were mounted well away from the sensing volumes.

C. TRIPODS & MOORINGS

Each tripod was equipped with either a Seabird Electronics Seagauge (SBE 26-03) or Seacat (SBE 16-04) sensor to record salinity, temperature and conductivity. Each Seacat had one additional data acquisition port, which was used to accommodate either a strain-gauge pressure sensor or an OBS. See Figure 3 and Table 1 for specific details. A Self-Contained Acoustic Doppler Current Profiler (ADCP), manufactured by RD Instruments, was placed on a tripod to observe horizontal velocity at 1 meter intervals from 1.5 to 15.5 meters above the sensor. InterOcean Systems Model S4 current meters were placed on top of three tripods (D, E and F) to provide horizontal velocity at 1 meter above bottom.

Two tripods (E and F) were equipped with adjacent moorings (Figure 3) to measure conductivity, temperature and optical backscatter 1 meter below the surface.

As seen in Figure 4, the central mooring, or C-mooring, was equipped to observe salinity, temperature and conductivity profiles at 4.3, 6.3, 8.3 10.3 and 12.3 meters below the surface. At 2.7 meters depth, an S4 current meter was equipped to measure conductivity, temperature and pressure, as well as horizontal velocity. OBS cells were mounted to provide estimates of turbidity from depths of 4.3 to 10.3 meters. The Seacat at the bottom of the C-mooring (12.3 meters deep) was equipped with a strain-gauge pressure sensor.

---

1 Seabird Electronics, Inc., Bellevue, WA 98005
2 D&A Instrument Company, Port Townsend, WA
3 ParoScientific, Redmond, WA 98052
4 RD Instruments, San Diego, CA 92131
5 InterOcean Systems, Inc., San Diego, CA 92123-1799
Surlyn Surface Buoy
2m 1/2" Chain
9.5m 3/8" Chain
500 lb Anchor

28" Steel Sphere
EG&G Release
SEACAT Pressure
1/2m 3/8" Chain
100m Ground Line

300 lb Tripod

300 lb Tripod

EG&G Release
SEACAT Pressure
1/2m 3/8" Chain
100m Ground Line

300 lb Tripod

Figure 3. Schematic of Tripods & Moorings (not to scale)

NOTE: The F-Tripod is similar to the E-Tripod. The differences in the F-Tripod are noted in parenthesis.
Figure 4. Central Mooring Schematic

NOTE: The S4 current meter was equipped with temperature and conductivity sensors.
D. SHIPBOARD INSTRUMENTATION

The shipboard measurements were performed from the 24' R/V Mytilus (Woods Hole Oceanographic Institution). Instrumentation included:

- an Ocean Sensors\textsuperscript{6} CTD profiler (OS200) equipped with an optical backscatterance sensor (D&A Instruments) to measure temperature, salinity, pressure and suspended sediment concentration;
- a 1.2 mHz narrow-band Acoustic Doppler Current Profiler (ADCP, RD Instruments), providing vertical profiles of velocity beneath the vessel;
- a holey-sock drogue, 1-m diameter and 2-m in length, centered at 3.5 meters depth for tracking subsurface currents;
- a Klien (Model 595) sidescan sonar operating at 100 and 500 kHz for recording images of bottom slope variation.

E. METEOROLOGICAL INSTRUMENTATION

Wind speed and direction, air temperature, relative humidity, and atmospheric pressure were collected and processed using a Coastal Environmental Systems\textsuperscript{7} Weatherpak-2000 meteorological package.

\textsuperscript{6} Ocean Sensors, San Diego, CA 92121
\textsuperscript{7} Coastal Environmental Systems, Seattle, WA 98104
SECTION III

DEPLOYMENTS & SAMPLING SCHEMES
Figure 5. USGS NOS Bathymetry Survey (1934)
A. OVERVIEW

The deployment sites are shown in Figure 5 with the 1934 NOS bathymetry contours. Site A is not shown on this figure and is 3 km seaward of B, as shown in Figure 1. The six tripods and three moorings were onsite from mid-August through the end of October. (See Table 2.) The BASS quadrapod was deployed for two two-week periods, one at the beginning and the other at the end of the study, each spanning one spring-neap tidal cycle.

The C-mooring and tripods A, B and D were deployed in the deepest part of the channel, while Tripods E and F, along with their respective moorings, were deployed on a shelf along the west side of the channel. The BASS quadrapod and the ADCP-Tripod were deployed cross-channel from the central mooring site (Figure 6).

Shipboard CTD surveys were conducted at mooring locations, as well as on along-channel and cross-channel transects, throughout each of the BASS deployment periods. (See Table 3.) Velocity data supplemented the CTD data during transverse and turbidity maximum surveys.

Table 2. SUMMARY OF DEPLOYMENTS 
(ordered by time of deployment)

<table>
<thead>
<tr>
<th>Instrument ID</th>
<th>Time In/Out (EDT)</th>
<th>Location Degrees Minutes</th>
</tr>
</thead>
<tbody>
<tr>
<td>C-mooring</td>
<td>8/15/95 17:30</td>
<td>40° 47.47' N</td>
</tr>
<tr>
<td></td>
<td>10/26/95 13:10</td>
<td>73° 59.24' W</td>
</tr>
<tr>
<td>E-trpod &amp; E-mooring</td>
<td>8/15/95 18:32</td>
<td>40° 47.92'</td>
</tr>
<tr>
<td></td>
<td>10/26/95 9:50</td>
<td>73° 59.52'</td>
</tr>
<tr>
<td>F-trpod &amp; F-mooring</td>
<td>8/15/95 19:18</td>
<td>40° 49.20'</td>
</tr>
<tr>
<td></td>
<td>10/26/95 10:45</td>
<td>73° 58.36'</td>
</tr>
<tr>
<td>ADCP-trpod</td>
<td>8/16/95 11:39</td>
<td>40° 47.49'</td>
</tr>
<tr>
<td></td>
<td>10/26/95 09:00</td>
<td>73° 59.33'</td>
</tr>
<tr>
<td>D-trpod</td>
<td>8/16/95 12:22</td>
<td>40° 48.96'</td>
</tr>
<tr>
<td></td>
<td>10/26/95 12:25</td>
<td>73° 57.98'</td>
</tr>
<tr>
<td>B-trpod</td>
<td>8/16/95 12:40</td>
<td>40° 45.97'</td>
</tr>
<tr>
<td></td>
<td>10/26/95 08:30</td>
<td>74° 00.57'</td>
</tr>
<tr>
<td>A-trpod</td>
<td>8/16/95 14:05</td>
<td>40° 42.92'</td>
</tr>
<tr>
<td></td>
<td>10/26/95 07:50</td>
<td>74° 01.32'</td>
</tr>
<tr>
<td>BASS-quadrapod</td>
<td>8/16/95 16:58</td>
<td>40° 47.46'</td>
</tr>
<tr>
<td></td>
<td>8/30/95 8:53</td>
<td>73° 59.19'</td>
</tr>
<tr>
<td>Met</td>
<td>8/16/95 17:25</td>
<td>40° 47.35'</td>
</tr>
<tr>
<td></td>
<td>10/26/95 17:10</td>
<td>73° 59.02'</td>
</tr>
<tr>
<td>BASS-quadrapod</td>
<td>10/17/95 12:05</td>
<td>40° 47.48'</td>
</tr>
<tr>
<td></td>
<td>10/26/95 13:30</td>
<td>73° 59.20'</td>
</tr>
</tbody>
</table>
Figure 6. Cross-channel site locations are shown with CTD depths (dots) and estimate of bottom-profile (dash-dot).
B. QUADRAPOD

During August, 1995, the quadrapod was tested in 10 meters of water off the coast near the Woods Hole Oceanographic Institution. These data are not presented in this report.

For the Hudson River deployments, care was taken to align the front of the quadrapod with the primary component of the tidal flow. This minimized flow disturbance from the structure and the instrument pressure cases. Pre- and post-cruise zeroes were conducted by wrapping the sensing volume in plastic and dipping the instrument from the dock.

First deployment:
Pre-deployment zeroes were taken 04:00 - 05:00 GMT on 8/16/95. The quadrapod was deployed on August 16, 1995, approximately 100 meters east of the Central mooring site (C). The orientation was: compass (231° ± 1°), pitch (-0.44° ± 0.09°), roll (-2.38° ± 0.06°). The depth from the pressure sensor was 15.55 ± 0.44 meters. Every 10 minutes, three minutes of data were recorded (1230 samples at 160 millisecond intervals). Post-deployment estimates of zeros were taken from 13:50 - 16:40 GMT on 8/30/95.

Second deployment:
Pre-deployment estimates of zeros were taken from 17:30 - 18:00 GMT on 10/16/95. The instrument was deployed October 17, 1995, at the same location. The quadrapod was not oriented as closely to the tidal flow (13° from Deployment I): compass (218° ± 4°), pitch (-2.29° ± 0.06°), and roll (2.58° ± 0.02°). The depth from the pressure sensor was 15.38 ± 0.50 meters. Every 10 minutes, six minutes of data were recorded (2220 samples at 170 millisecond intervals). Post-deployment estimates of zeros were taken on 10/26/95 (19:51 GMT).

C. TRIPODS & MOORINGS

The C-mooring was deployed at the deepest part of the channel along the central transect of the experiment region. The Seacats with OBS sensors sampled every 5 minutes; the Seacat with the pressure sensor sampled every 20 minutes; and the S4 with pressure recorded a three minute average every 20 minutes.

Tripods A, B and D were also placed in the deepest cross-channel location at positions along the river (Figure 1). The Seagauge sensors were programmed to record a 20 minute average every 20 minutes. The S4 recorded 3 minute averages of 2Hz data every 10 minutes.

Tripods E and F, with the attached moorings, were placed on a shelf on the western side of the channel. The Seagauges on the tripods sampled every 20 minutes, while the S4s recorded 3 minute averages of 2Hz data every 10 minutes. The Seacat on the E-mooring sampled every 5 minutes and the Seacat on the F-mooring sampled every 20 minutes.

The ADCP tripod was deployed approximately 140 meters west of the central mooring site and was configured to provide 15 one-meter depth bins centered at 1.5 to 15.5 meters above bottom. The ADCP was set up to record 9 minute averages every 10 minutes (with 200 pings/ensemble). The Seagauge (with pressure) recorded 20 minute averages every 20 minutes.

D. SHIPBOARD OBSERVATIONS

The CTD was hand-lowered at approximately 1 m/s to within 0.25 meters of the bottom during each cast. A wooden dowel was used to prevent the sensors from touching the bottom. The sampling rate was 10 Hz, yielding a vertical resolution of 10 cm. The ADCP transducer was fixed to the side of the ship at 0.3-m depth, providing velocity data at 1-m intervals from 1.3m below the surface to within 15% of the total water depth. The last 15% was contaminated by the bottom return. Velocity relative to the bottom was determined by bottom
Five types of surveys were conducted throughout the experiment: transverse, long, longitudinal, turbidity maximum, and yo-yo anchor stations. (See Table 4.)

Transverse sections were conducted approximately hourly during each observation period, sampling across the channel at the central mooring site and about 3 km upstream and downstream of the central mooring (at Sites B and D/F). These surveys included ADCP velocity, as well as CTD and OBS profiles.

Four long surveys were conducted from the Battery (0 km) to approximately 1psu salinity (61 - 110 km).

Four detailed longitudinal sections were conducted along approximately 28 km of the river section centered around the Central Mooring site (Site C), following the deepest part of the channel.

Four local surveys between the central mooring site and the northern transect (Site D/F) were conducted primarily on the western bank to 10 meters to study the turbidity maximum.

Two yo-yo casts were conducted at anchor stations to detect internal waves, but have not been processed to date.

Table 3. SUMMARY OF SHIPBOARD SURVEYS

<table>
<thead>
<tr>
<th>Date (EDT)</th>
<th>Day #</th>
<th>Survey Type</th>
<th>Along-Channel Location</th>
</tr>
</thead>
<tbody>
<tr>
<td>8/15/95 16:18</td>
<td>1</td>
<td>Side Scan Sonar</td>
<td>10.3 ± 0.2 KM</td>
</tr>
<tr>
<td>8/17/95 8:15 - 19:05</td>
<td>3</td>
<td>(4) longitudinal sections</td>
<td>-4 to 25 KM</td>
</tr>
<tr>
<td>8/18/95 7:05 - 19:10</td>
<td>4</td>
<td>(10 each) transverse sections</td>
<td>@ 7, 10 &amp; 14 KM</td>
</tr>
<tr>
<td>8/20/95 10:28 - 17:35</td>
<td>6</td>
<td>1st long survey</td>
<td>0 to 96 KM</td>
</tr>
<tr>
<td>8/21/95 8:59 - 19:13</td>
<td>7</td>
<td>1st turb. max survey</td>
<td>11 to 13 KM</td>
</tr>
<tr>
<td>8/22/95</td>
<td>8</td>
<td>Side Scan Sonar</td>
<td>12 ± 2 KM</td>
</tr>
<tr>
<td>8/23/95 8:20 - 18:52</td>
<td>9</td>
<td>2nd turb. max survey</td>
<td>11 to 13 KM</td>
</tr>
<tr>
<td>8/24/95 7:21 - 16:57</td>
<td>10</td>
<td>3rd turb. max survey</td>
<td>11 to 13 KM</td>
</tr>
<tr>
<td>8/25/95 7:27 - 18:03</td>
<td>11</td>
<td>4th turb. max survey</td>
<td>12 to 13 KM</td>
</tr>
<tr>
<td>8/27/95 7:53 - 17:36</td>
<td>13</td>
<td>(4) longitudinal sections</td>
<td>-4 to 24 KM</td>
</tr>
<tr>
<td>8/28/95 7:28 - 19:37</td>
<td>14</td>
<td>(11 each) transverse sections</td>
<td>@ 7, 10 &amp; 14 KM</td>
</tr>
<tr>
<td>8/29/95 9:14 - 13:01</td>
<td>15</td>
<td>2nd long survey</td>
<td>0 to 110 KM</td>
</tr>
<tr>
<td>10/16/95 16:34 - 20:36</td>
<td>16</td>
<td>3rd long survey</td>
<td>0 to 106 KM</td>
</tr>
<tr>
<td>10/17/95 7:45</td>
<td>17</td>
<td>yo-yo anchor station</td>
<td></td>
</tr>
<tr>
<td>10/18/95 7:38 - 17:43</td>
<td>18</td>
<td>4 longitudinal sections</td>
<td>-4 to 24 KM</td>
</tr>
<tr>
<td>10/19/95 7:40 - 19:52</td>
<td>19</td>
<td>(11 each) transverse sections</td>
<td>@ 7, 10 &amp; 14 KM</td>
</tr>
<tr>
<td>10/20/95 7:49 - 19:07</td>
<td>20</td>
<td>4 longitudinal sections</td>
<td>-4 to 24 KM</td>
</tr>
<tr>
<td>10/21/95 7:32 - 14:27</td>
<td>21</td>
<td>(4) transverse sections</td>
<td>@ 7, 10 &amp; 14 KM</td>
</tr>
<tr>
<td>10/22/95 15:34 - 01:45</td>
<td>22</td>
<td>3 longitudinal sections</td>
<td>-4 to 24 KM</td>
</tr>
<tr>
<td>10/23/95 7:27 - 18:53</td>
<td>23</td>
<td>(10-11 each) transverse sections</td>
<td>@ 7, 10 &amp; 14 KM</td>
</tr>
<tr>
<td>10/24/95</td>
<td>24</td>
<td>yo-yo anchor station</td>
<td></td>
</tr>
<tr>
<td>10/25/95 11:38 - 14:20</td>
<td>25</td>
<td>4th long survey</td>
<td>0 to 61 KM</td>
</tr>
</tbody>
</table>
D. METEOROLOGICAL STATION

The WeatherPak was installed at the 79th Street Boat Basin, which was along the transect of the ADCP tripod, BASS quadrapod and the central mooring. The unit was strapped to along-channel pilings, with the sensing volume at approximately 4 meters above the mean water level. Five (5) minute averages every 5 minutes were recorded.
SECTION IV

DATA PROCESSING
A. OVERVIEW

This section documents the details of data processing. Section B describes the processing of data from the quadrupod; Section C from the moorings and tripods; Section D from the shipboard systems; and Section E from the meteorological data.

B. BASS QUADRUPOD

BASS Velocity

Data were unpacked, corrected for zeros (Morrison, 1993) and converted into along (up channel) and cross channel (toward New Jersey) velocity.

Table 4. Summary of Determination of BASS Zeros (m/s)

<table>
<thead>
<tr>
<th>ACM:Axis/Pod</th>
<th>8/15/95 mean</th>
<th>8/31/95 mean</th>
<th>10/16/95 mean</th>
<th>10/26/95 mean</th>
<th>8/95 used</th>
<th>10/95 used</th>
</tr>
</thead>
<tbody>
<tr>
<td>1:Axis A/1</td>
<td>-0.004</td>
<td>-0.005</td>
<td>-0.004</td>
<td>-0.005</td>
<td>-0.005</td>
<td>-0.005</td>
</tr>
<tr>
<td>2:Axis B/1</td>
<td>-0.011</td>
<td>-0.001</td>
<td>*BAD</td>
<td>BAD</td>
<td>BAD</td>
<td>BAD</td>
</tr>
<tr>
<td>3:Axis C/1</td>
<td>-0.000</td>
<td>0.003</td>
<td>0.000</td>
<td>0.002</td>
<td>0.000</td>
<td>0.000</td>
</tr>
<tr>
<td>4:Axis D/1</td>
<td>-0.006</td>
<td>-0.001</td>
<td>-0.001</td>
<td>-0.002</td>
<td>-0.004</td>
<td>-0.001</td>
</tr>
<tr>
<td>5:Axis A/2</td>
<td>0.002</td>
<td>0.008</td>
<td>0.000</td>
<td>-0.000</td>
<td>BAD</td>
<td>BAD</td>
</tr>
<tr>
<td>6:Axis B/2</td>
<td>0.003</td>
<td>0.006</td>
<td>0.002</td>
<td>0.002</td>
<td>0.005</td>
<td>0.002</td>
</tr>
<tr>
<td>7:Axis C/2</td>
<td>-0.001</td>
<td>-0.002</td>
<td>0.000</td>
<td>-0.003</td>
<td>-0.002</td>
<td>0.000</td>
</tr>
<tr>
<td>8:Axis D/2</td>
<td>0.002</td>
<td>0.000</td>
<td>0.002</td>
<td>0.003</td>
<td>0.002</td>
<td>0.002</td>
</tr>
<tr>
<td>9:Axis A/3</td>
<td>0.007</td>
<td>0.009</td>
<td>0.012</td>
<td>0.008</td>
<td>0.008</td>
<td>0.012</td>
</tr>
<tr>
<td>10:Axis B/3</td>
<td>0.004</td>
<td>-0.008</td>
<td>BAD</td>
<td>-0.006</td>
<td>0.000</td>
<td>0.000</td>
</tr>
<tr>
<td>11:Axis C/3</td>
<td>-0.007</td>
<td>-0.007</td>
<td>-0.012</td>
<td>-0.010</td>
<td>-0.007</td>
<td>-0.012</td>
</tr>
<tr>
<td>12:Axis D/3</td>
<td>-0.003</td>
<td>0.010</td>
<td>BAD</td>
<td>BAD</td>
<td>BAD</td>
<td>BAD</td>
</tr>
<tr>
<td>13:Axis A/4</td>
<td>-0.006</td>
<td>-0.004</td>
<td>BAD</td>
<td>BAD</td>
<td>-0.005</td>
<td>BAD</td>
</tr>
<tr>
<td>14:Axis B/4</td>
<td>0.008</td>
<td>0.007</td>
<td>0.000</td>
<td>0.004</td>
<td>0.007</td>
<td>0.000</td>
</tr>
<tr>
<td>15:Axis C/4</td>
<td>0.005</td>
<td>0.004</td>
<td>0.003</td>
<td>0.005</td>
<td>0.004</td>
<td>0.003</td>
</tr>
<tr>
<td>16:Axis D/4</td>
<td>-0.010</td>
<td>-0.011</td>
<td>-0.003</td>
<td>-0.007</td>
<td>-0.010</td>
<td>-0.003</td>
</tr>
<tr>
<td>17:Axis A/5</td>
<td>-0.002</td>
<td>-0.003</td>
<td>-0.004</td>
<td>-0.004</td>
<td>-0.002</td>
<td>-0.004</td>
</tr>
<tr>
<td>18:Axis B/5</td>
<td>0.002</td>
<td>0.006</td>
<td>-0.001</td>
<td>0.000</td>
<td>0.000</td>
<td>-0.001</td>
</tr>
<tr>
<td>19:Axis C/5</td>
<td>0.002</td>
<td>0.006</td>
<td>0.001</td>
<td>0.004</td>
<td>0.004</td>
<td>0.001</td>
</tr>
<tr>
<td>20:Axis D/5</td>
<td>-0.001</td>
<td>-0.002</td>
<td>0.001</td>
<td>BAD</td>
<td>-0.002</td>
<td>0.001</td>
</tr>
</tbody>
</table>

* (BAD) These axes had no data or frequent periods of bad data.

Each sensor, or pod, is numbered 1 to 5 (bottom to top). Some axes did not work properly, or at all, and were reconstructed from the remaining three axes of the affected pod: Deployment I & II: Axis B (Pod 1) Axis A (Pod 2), Axis D (Pod 3); Deployment II (only): Axis A, Pod 4.

The existence of an intermittent problem in the BASS electronics caused the recorded velocities to jump to values far from the tidal signal. These data were replaced with NaNs. Fewer than 4% of the bursts had more than 4% of the burst flagged bad because of this problem.

Another condition existed around 8/26/95 when severely reduced velocities persisted over a few tidal cycles, varying amongst sensors 1 through 3 (moving after tidal changes). These periods were flagged as NaN in the
burst averaged and hourly averaged data only.

**Quadrapod Pressure, Conductivity & Temperature**

These data were all collected using counters (Williams 1995). For reasons not understood, this sampling technique introduced a noise floor which limits the effective sampling frequency to a factor of 10 lower than the Nyquist frequency. These problems were more severe during the October deployment.

Sediment trapped in the conductivity cells caused the salinity to appear lower than actual conditions; therefore, small vertical gradients in salinity may be unreliable.

For the second deployment (October 1995), it was apparent that the top-most SeaBird conductivity cell was faulty and is not included in the data set.

Conductivity and temperature data were converted to world units using coefficients from the September, 1995, SeaBird calibrations.

Modifications by ParoScientific to their pressure gauges provide temperature frequencies to be used to correct the pressure signal for temperature effects. During the Hudmix experiment, the pressure sensor temperature frequency was not recorded, so a lookup table of temperature and temperature frequency was obtained from ParoScientific. SeaBird temperature was used with the lookup table (tcal.mat) to correct the pressure for temperature.

**Quadrapod OBS**

These data show strong tidal fluctuations but have not been calibrated with sediment concentration, and remain as counts. The processed data had each sensor’s daily observed baseline subtracted (in counts), as follows: all counts greater than 60000 were discarded as outliers; then, for each sensor, the 20th percentile of the cumulative frequency distribution was identified and subtracted from the data; finally, all values less than zero were assigned to be zero. An approximate calibration based on comparison with the shipboard OBS measurements (8/28 and 10/23/95), which were calibrated against water samples, is a linear relationship between counts and sediment concentration, with no offset, and with the maximum observed concentration equal to the maximum shipboard concentration: for Deployment I, 800 counts is roughly 60 mg/l; for Deployment II, 4000 counts is roughly 200 mg/l.

**C. MOORED & TRIPOD DATA**

Instruments were synchronized by the application of appropriate time offsets for each instrument. Hourly averages were computed from measurements by applying a one-hour boxcar filter and interpolating values to obtain on-hour estimates.

**Tripod Salinity**

As seen in the quadrapod sensors, sediment accumulation in the tripod conductivity sensors caused significant errors in salinity. Ad hoc corrections were made to yield stable stratification and to minimize differences from the shipboard CTD. Apparent anomalies in salinity were removed; then, salinity from B-tripod was detrended, based on a comparison with the A-tripod and C-mooring data; and salinity from D-tripod was detrended (piecewise), based on comparison with C-mooring data. Fouling of the conductivity cells in the bottom sensors make the use of near-bottom vertical salinity gradients unreliable, but data can confidently be used to document tidal variability.
Tripod Pressure

Seagauge pressure data were corrected for atmospheric pressure with the time series of barometric pressure from the met data. Pressure data from the central mooring Seacat and from the F-tripod Seacat were detrended.

ADCP Velocity

Data were rotated into along and across channel coordinates by determining the angle of maximum variance (46.1° from Magnetic North). From the tilt and compass, it can be seen that the ADCP tripod was disturbed on October 23 (Day 295). First it moved near the maximum ebb flow and then, 6 hours later, near maximum flood flow. The ADCP velocities during the six hour time period appeared faulty, indicating flow obstruction, and were removed from the data set.

S4 Velocity

S4 data from the central mooring, D Tripod, E Tripod and F Tripod were rotated to along-channel velocity components, based on the angle of maximum variance: 45.2°, 44.7°, 54.3° and 55.2° from Magnetic North, respectively.

Tripod and Moored OBS Data

The moored OBS data (volts) were noisy, with drift problems, and have not been calibrated; they are subsequently not discussed in this report.

D. SHIPBOARD DATA

CTD Data

Until August 25, the salinities from the CTD are consistent with the moored salinity sensors. After August 25, CTD salinity measurements appear 0.8-1 psu too low. This is most likely due to damage to the sensor during near-bottom sampling. Data from each CTD cast was vertically averaged into 25-cm increments.

ADCP Data

Current meter data collected from the shipboard ADCP were converted into along and across channel components using the angle of maximum variance to determine the along channel direction. The shipboard ADCP velocity measurements were interpolated in space to obtain the velocities corresponding to the CTD's vertically averaged data. In addition, high frequency (10-second to 1-minute period) fluctuations in the ADCP velocities due to bottom tracking errors were filtered out by applying a sixth order polynomial fit to the data. All measurements were graphically analyzed to remove outlying data points.

OBS Data

The OS200/OBS hand profiler was calibrated using the OBS on the small tripod called Gafanhoto, used in a companion study of sediment transport, which was calibrated against water samples. In the lab comparisons, the gain of the two instruments over a range of concentrations was within 2%. Shipboard OBS data are documented in Orton (1995).

E. METEOROLOGICAL DATA

Met data were converted from wind speed and direction to oceanographic fluid velocity, using the angle of maximum variance (19.6° from Magnetic North) to rotate northward and eastward flow into along and across channel velocity.
SECTION V

DATA SUMMARY
A. OVERVIEW

In this chapter, time series and contours of the data provide an overview of sampling durations and data ranges. The plots are grouped by deployment type: quadrapod (Section B), tripods and moorings (Section C), shipboard data contours (Section D) and meteorological data (Section E).

Section F contains comparisons of ADCP velocity, temperature and salinity with those of BASS at the same time and depth, together with a comparison of ADCP temperature and salinity with corresponding central mooring observations. The 79th Street wind velocities are compared with the National Data Buoy Center (NOAA) buoy wind velocity.

B. QUADRAPOD

Time series of each of the quadrapod deployments are presented in figures 7 - 12.
Figure 7. Quadrapod: Temperature & Salinity (Deployment I)

Day in August (1995)
Figure 8. Quadrapod: Pressure & OBS (Deployment 1)

(800 counts corresponds to approximately 60 mg/l)

Day in August (1995)
Figure 9. Quadrapod: Horizontal Velocity (Deployment I)

Day in August (1995)
Figure 10. Quadrapod: Temperature & Salinity (Deployment II)
Figure 11. Quadrapod: Pressure & OBS (Deployment II)
Figure 12. Quadrapod: Horizontal Velocity (Deployment II)
C. TRIPODS & MOORINGS

Time series of the tripod and mooring data are presented in figures 13 - 34.
Figure 13. Tripod A: Temperature & Salinity
Figure 15. Tripod B: Temperature & Salinity
Figure 17. Central Mooring: Temperature
Figure 18. Central Mooring: Salinity
Figure 20. Central Mooring: Horizontal Velocity
Figure 22. ADCP Tripod: Pressure
Figure 23. ADCP Tripod: Along-Channel Velocity (2.5, 5.5, 8.5 and 11.5 meters above bottom)
Figure 24. ADCP Tripod: Cross-Channel Velocity (2.5, 5.5, 8.5 and 11.5 meters above bottom)
Figure 25. Tripod D: Temperature & Salinity
Figure 27. Tripod D: Horizontal Velocity

(Note fouling of sensor.)
Figure 28. Mooring E: Temperature & Salinity
Figure 30. Tripod E: Horizontal Velocity
(Note noise in cross-channel velocity (v).)
Figure 31. Mooring F: Temperature & Salinity
Figure 32. Tripod F: Temperature & Salinity
Figure 34: Tripod F: Horizontal Velocity
Based on grab and core samples, pattern 1 coincides with easily erodible sediment while pattern 4 coincides with less erodible material.
D. SHIPBOARD DATA

Side-scan sonar results are summarized in figure 35.

Salinity and temperature contours of the longitudinal surveys are presented in figures 36 - 40. The mean hourly averaged velocities (mean of ADCP bins at 4.5, 6.5, 8.5, 10.5 and 11.5 meters) are included at the bottom of each page, with the patches representing the time of each survey.

Velocity and salinity contours of the transect surveys are presented in figures 41 - 55.

The mean hourly averaged velocities (as described above) are included for the days when long surveys were conducted (Figure 56). Salinity and temperature contours of the long surveys are presented in figures 57 - 60.
Figure 36a. Longitudinal Survey (8/17/95): Salinity Contour

- Line 1: 0814-0951
- Line 2: 1115-1246
- Line 3: 1456-1642
- Line 4: 1739-1904

Distance from Battery, km

Velocity, m/s

Hour (EDT) 8/17/95
Figure 36b. Longitudinal Survey (8/17/95): Temperature Contour

- Line 1: 0814-0954
- Line 2: 1115-1246
- Line 3: 1456-1642
- Line 4: 1739-1904

Depth, m:
- 0
- 5
- 10
- 15
- 20

Distance from Battery, km:
- 0
- 5
- 10
- 15
- 20

Hour (EDT) 8/17/95
Figure 37a. Longitudinal Survey (8/27/95): Salinity Contour

- Line 1: 0752–0915
- Line 2: 1022–1137
- Line 3: 1247–1419
- Line 4: 1541–1735

Distance from Battery, km

Hour (EDT) 8/27/95

Velocity, m/s
Figure 37b. Longitudinal Survey (8/27/95): Temperature Contour

- Line 1: 0752-0915
- Line 2: 1022-1137
- Line 3: 1247-1419
- Line 4: 1541-1735

Depth, m

Distance from Battery, km

Hour (EDT) 8/27/95
Figure 38a. Longitudinal Survey (10/18/95): Salinity Contour

- Line 1: 0738-0904
- Line 2: 1028-1218
- Line 3: 1347-1509
- Line 4: 1627-1742

Depth, m

Distance from Battery, km

Velocity, m/s

Hour (EDT) 10/18/95

68
Figure 39a. Longitudinal Survey (10/20/95): Salinity Contour

- Line 1: 0748-0917
- Line 2: 1116-1251
- Line 3: 1439-1610
- Line 4: 1733-1906

Depth, m

Distance from Battery, km

Hour (EDT) 10/20/95

Velocity, m/s

1
0
-1

8 10 12 14 16 18
Figure 39b. Longitudinal Survey (10/20/95): Temperature Contour

- Line 1: 0748–0917
- Line 2: 1116–1251
- Line 3: 1439–1610
- Line 4: 1733–1906

Distance from Battery, km

Hour (EDT) 10/20/95

Velocity, m/s

0 1 2
Figure 40a. Longitudinal Survey (10/22/95): Salinity Contour

- **Line 1**: 0817-0957
- **Line 2**: 1132-1354
- **Line 3**: 1612-1745

- Depth, m
- Distance from Battery, km

- Velocity, m/s
- Hour (EDT) 10/22/95
Figure 40b. Longitudinal Survey (10/22/95): Temperature Contour

- Line 1: 0817-0957
- Line 2: 1132-1354
- Line 3: 1612-1745

Depth, m

Distance from Battery, km

Velocity, m/s

Hour (EDT) 10/22/95
Figure 41a. South transect, salinity contours (psu) on 8/18/95
Figure 41b. South transect, velocity contours (cm/s) on 8/18/95
Figure 42a. Middle transect, salinity contours (psu) on 8/18/95
Figure 42b. Middle transect, velocity contours (cm/s) on 8/18/95
Figure 43a. North transect, salinity contours (psu) on 8/18/95
Figure 43b. North transect, velocity contours (cm/s) on 8/18/95
Figure 44a. South transect, salinity contours (psu) on 8/28/95
Figure 44b. South transect, velocity contours (cm/s) on 8/28/95
Figure 45a. Middle transect, salinity contours (psu) on 8/28/95
Figure 45b. Middle transect, velocity contours (cm/s) on 8/28/95
Figure 46a. North transect, salinity contours (psu) on 8/28/95
Figure 46b. North transect, velocity contours (cm/s) on 8/28/95
Figure 47a. South transect, salinity contours (psu) on 10/19/95
Figure 47b. South transect, velocity contours (cm/s) on 10/19/95
Figure 48a. Middle transect, salinity contours (psu) on 10/19/95
Figure 48b. Middle transect, velocity contours (cm/s) on 10/19/95
Figure 49a. North transect, salinity contours (psu) on 10/19/95
Figure 49b. North transect, velocity contours (cm/s) on 10/19/95
Figure 50a. South transect, salinity contours (psu) on 10/21/95
Figure 50b. South transect, velocity contours (cm/s) on 10/21/95
Figure 51a. Middle transect, salinity contours (psu) on 10/21/95
Figure 51b. Middle transect, velocity contours (cm/s) on 10/21/95
Figure 52a. North transect, salinity contours (psu) on 10/21/95
Figure 52b. North transect, velocity contours (cm/s) on 10/21/95
Figure 53a. South transect, salinity contours (psu) on 10/23/95
Figure 53b. South transect, velocity contours (cm/s) on 10/23/95
Figure 54a. Middle transect, salinity contours (psu) on 10/23/95
Figure 54b. Middle transect, velocity contours (cm/s) on 10/23/95
Figure 55a. North transect, salinity contours (psu) on 10/23/95
Figure 55b. North transect, velocity contours (cm/s) on 10/23/95
Figure 56. Long Survey Tidal Cycles
(vertically averaged velocity, 8.3 mab, from ADCP)
Figure 57. Long Survey (8/20/95): Temperature & Salinity Contours
Figure 58. Long Survey (8/29/95): Temperature & Salinity Contours
Figure 59. Long Survey (10/16/95): Temperature & Salinity Contours
Figure 60. Long Survey (10/25/95): Temperature & Salinity Contours
E. METEOROLOGICAL DATA

Relative humidity, atmospheric pressure, and air temperature are plotted in figure 61a. Figure 61b shows battery voltage and horizontal wind speed. The along-channel velocity (u) and cross-channel velocity (v) are in oceanographic direction, corresponding to the other velocity measurements (+u indicates flow toward the up-channel direction; +v indicates flow toward New Jersey).
Figure 61b. MET Station Battery Voltage & Horizontal Velocity
Comparison of Depth Gauges at ADCP and BASS sites

Figure 62. Hourly Averaged Quadrapod depth vs. ADCP depth (meters)
F. DATA CONSISTENCY CHECKS

ADCP with BASS Pressure

A comparison of hourly averaged pressure records from the ADCP tripod are shown with those from the BASS quadrapod for each of the BASS deployments in figure 62.

ADCP with BASS Velocity

Figures 63a (August deployment) and 63b (October deployment) suggest the existence of flow disturbance in the lowest two and the top-most bins of the ADCP profiles (bins 1,2 & 12), possibly from the tripod structures. A shift in velocity between alternate bins can also be seen which resulted from the selection of the smallest bin size (Terry Chereskin, Scripps, personal communication).

Temperature/Salinity Comparisons

Figures 64 and 65 show good agreement of temperature and salinity when comparing the ADCP Seagaug observations with either the lowest Seacat at the Central Mooring or the BASS Seabirds at 1.1 meters above bottom.

MET Station / NDBC Wind Velocity Comparisons

Comparison of the meteorological data from the National Data Buoy Center (NOAA) buoy off Long Island with the HUDMIX wind data, shown in figure 66), suggests that the 79th MET station Weatherpak was obstructed when wind was blowing toward New Jersey (Figure 66).
Figure 63a. Comparison of ADCP along-channel velocity with BASS (Deployment I)

8/17 - 8/30/95 (S4 on Central Mooring (*) - ADCP (+) - BASS (o)

Mean Along-Channel Flow (m/s)

Height Above Bottom (m)
Figure 63b. Comparison of ADCP along-channel velocity with BASS (Deployment II)
Figure 64. Comparison of Quadrapod Temperature and Salinity (at 1.1 mab) with the ADCP Temperature and Salinity (at 0.9 mab)

Figure 65. Comparison of C-mooring Temperature and Salinity (lowest sensor) with the ADCP Temperature and Salinity (at 0.9 mab)
Figure 66. Comparison of MET Station wind velocities with the CMAN NDBC wind velocity (along with site of NDBC buoy).
A. OVERVIEW

This section contains documentation of basic and processed data files, providing a history of the data and a guide for the use of the processed data files.

B. BASS QUADRAPOD DATA FILES

1. Raw Data formats, as recorded by the BASS data logger

<table>
<thead>
<tr>
<th>Deployment I</th>
<th>Variable</th>
<th># variables</th>
<th>bytes/variable</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Keyword(AB06)</td>
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<td>2</td>
</tr>
<tr>
<td></td>
<td>Timeword</td>
<td>5</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>Travel Time</td>
<td>5</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>OBS</td>
<td>5</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>pitch</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>roll</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>ACM</td>
<td>20</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>compass</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>pressure</td>
<td>1</td>
<td>4</td>
</tr>
<tr>
<td></td>
<td>SeaBirds</td>
<td>8</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>Total bytes/record:</td>
<td></td>
<td>93</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Deployment II</th>
<th>Variable</th>
<th># variables</th>
<th>bytes/variable</th>
</tr>
</thead>
<tbody>
<tr>
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<td>Keyword(AB07)</td>
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<td>2</td>
</tr>
<tr>
<td></td>
<td>Timeword</td>
<td>5</td>
<td>1</td>
</tr>
<tr>
<td></td>
<td>Travel Time</td>
<td>10</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>OBS</td>
<td>5</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>pitch</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>roll</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>ACM</td>
<td>20</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>compass</td>
<td>1</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>pressure</td>
<td>1</td>
<td>4</td>
</tr>
<tr>
<td></td>
<td>SeaBirds</td>
<td>8</td>
<td>2</td>
</tr>
<tr>
<td></td>
<td>Total bytes/record:</td>
<td></td>
<td>103</td>
</tr>
</tbody>
</table>

Data are stored in the order listed above. Timeword is GMT: day, hour, minute, second and counter (0-255). Travel Time, OBS, pitch, roll, ACMs, compass, pressure and SeaBirds are logged as counts.

2. Full Burst Data

Horizontal and vertical velocity were stored in half-day sets. Each half day has two files: v_doy_N.mat and v_vels_N.mat. N represents the unblocking count and can be associated with the date and time of the data by using the associative table in fnlist.

In the 'doy' file:

doy - the day in the experiment month (i.e., doy=24.5 from the August data set is noon on August 24th). Breaks between bursts can be detected by looking for gaps greater than 2 minutes.

In the 'vels' file:

w - contains the horizontal velocity (m/s) with the real part representing the along-channel flow and the imaginary part representing cross-channel flow (toward New Jersey).
upAC/upBD - represent vertical velocity (m/s)
3. 10 minute Burst Averaged Data

Zmeans: heights of the five BASS sensors, OBS sensors and conductivity cells.

The burst averaged data (every ten minutes) were in Matlab® files as follows:

**Vmeans:**
- wmean, wstd - burst average, std
  - real part is the along-stream velocity (+ - upstream) (m/s)
  - imaginary part is the cross-stream velocity (+ - toward NJ) (m/s)
- mdoy - day of month (GMT) (August or October)

**Vmean2:**
- emean - number of bad points in each axis within each burst
- ccmeanN - six member correlation coefficients where N=1:5 (sensor)
  - and ccmeanN(:,1) = corrcoeff(u,v)
  - ccmeanN(:,2) = corrcoeff(u,wac)
  - ccmeanN(:,3) = corrcoeff(u,wbd)
  - ccmeanN(:,4) = corrcoeff(v,wac)
  - ccmeanN(:,5) = corrcoeff(v,wbd)
  - ccmeanN(:,6) = corrcoeff(wac,wbd)
- where: (u = along-channel flow; v = cross-channel flow;
  - wac = vertical from A/C axes; and wbd = vertical from B/D)
- wACmean(std) = burst average(std) of vertical velocity from axes A/C
- wBDmean(std) = burst average(std) of vertical velocity from axes B/D

(NOTE: When axes are reconstructed, wAC may be identical to wBD and the names may be misleading. Eg., if axis A is reconstructed, wAC is actually wBD.)

**TSmeans:**
- tmean, smean, cmean - burst average temperature (degrees Centigrade), salinity (o/oo), conductivity (Siemens/m)
- tstd,sstd,cstd - standard deviation within burst of temperature, salinity, conductivity
- temean - errors flagged within each burst (temperature, salinity, conductivity)

**Pmeans:**
- pmean(std) - burst average (std) of pressure (m) above sensor (1.56 mab)
- pmean - errors flagged within each burst

**PRCmeans:**
- cmean - mean compass reading (degrees) (updated hourly)
- pmean - mean pitch (degrees) (in A-C direction)
- rmean - mean roll (degrees) (in B-D direction)
- pstd,rstd - standard deviation of pitch, roll within burst

**Omeans:**
- omean - mean optical backscatter (counts) within burst with baseline removed
- ostd - standard deviation of backscatter within burst
- oemean - errors flagged within each burst

**ORmeans:**
(as above, but contains raw counts)

---

1 Mathworks, Inc., Natick, MA  01760
4. Hourly Averaged Data

The hourly averaged data are stored in one file for each deployment:

**hudmix b1 (8/95):**
- jdbass - day of year (EDT)
- ubass - hourly average up-stream velocity (m/s)
- vbass - hourly averaged cross-stream velocity (m/s) (+ toward New Jersey)
- ustd - hourly average of standard deviation within bursts in the along-stream direction (m/s)
- vstd - hourly average of standard deviation within bursts in the cross-stream direction (m/s)
- tmean, smean - hourly average temperature (degrees Centigrade), salinity (o/oo)
- omean - hourly average optical backscatter (processed counts)
- depth - hourly average depth (m) from pressure

**hudmix b2 (10/95):**
(same as above but jdbass was called jdbass2, etc.)
C. MET, TRIPOD & MOORED DATA FILES

1. Raw Data Files
For the purposes of this report, we have described the ASCII files which were converted from the binary files noted in parentheses.

ADCP: ASCII files HASC.NNN, where NNN=001-047, contain data which were converted from binary and scaled, corrected for pitch and roll, and converted to earth coordinates using adcpread.m. The format of the HASC files is in Table 4-2 (pp. 4-10 to 4-19) of the ADCP Manual (RD Instruments - March, 1991).

S4s: ASCII files hudM.asc, where M=mooring (c-f), can be read by reads4.m. Each file contains a header and description of each field.

Seagauges:
ASCII files hudMsgN.tid, where M is mooring(a-f) and N is the Seagauge ID, contains a sample id, date, time, pressure(psia), temperature (deg C), relative humidity (%), conductivity (Siemens/meter). These data can be read using readsg.m.

Seacats:

ASCII files:
(NOTE: hude_bot model 883 & hudetop is also model 883 one date 10/31 other 11/3 but data are the same)
 Hudc70.cnv: C mooring / SN 70
 Hudc71.cnv: C-mooring / SN 71
 Hudc72.cnv: C-mooring / SN 72
 Hudc73.cnv: C-mooring / SN 73
 Hudc884.cnv: C-mooring / SN 884
 Hude_bot.cnv: E-tripod
 Hudetop.cnv: E-mooring (seems to be same data as e_bot, but diff date)
 Hud68e.cnv: E-mooring / SN 68
 Hudfbot.cnv: F-tripod
 Hudftop.cnv: F-mooring

ASCII fields are described in headers.
These data can be read using readsc.m.

Met: ASCII file hudmet.asc contains unprocessed met data: date, time, wind speed (m/s), direction(degrees from north), sd,gust,lc, atmospheric temperature (deg C), barometric pressure (mbars) relative humidity (%), and battery voltage (V).
2. Hourly Averaged Data

Data were smoothed and stored as synchronized hourly averages in file hudmix_m.mat, which is summarized below:

jd - day of year (0.5 is noon on 1/1) (EDT)

at: air temp (deg C) from met station
bp: baro pressure (mbars) from met station
rh: relative humidity (percent) from met station
vbat: voltage, battery (can indicate sun coverage) from met station
uwind,vwind: wind speed (m/s) from met station (oceanographic flow)

t: temperature (deg C) from tripods and moorings
s: salinity (deg C) from tripods and moorings
c: conductivity (deg C) from tripods and moorings
p: pressure (dbars) from tripods and moorings
us4,vs4: velocity (m/s) from S4 current meters
obs: optical backscatter

Array descriptions:

<table>
<thead>
<tr>
<th>s4_name</th>
<th>s4_depth(m)</th>
<th>ts_name</th>
<th>ts_depth(m)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 c surface</td>
<td>3.2</td>
<td>1 atripod</td>
<td>17.0</td>
</tr>
<tr>
<td>2 d deep</td>
<td>19.5</td>
<td>2 btripod</td>
<td>17.0</td>
</tr>
<tr>
<td>3 e deep</td>
<td>7.2</td>
<td>3 cmooring--s4</td>
<td>2.7</td>
</tr>
<tr>
<td>4 f deep</td>
<td>6.5</td>
<td>4 cmooring--c1</td>
<td>4.3</td>
</tr>
<tr>
<td></td>
<td></td>
<td>5 cmooring--c2</td>
<td>6.3</td>
</tr>
<tr>
<td>p_name:</td>
<td>p_depth(m):</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1 atripod</td>
<td>17.0</td>
<td>6 cmooring--c3</td>
<td>8.3</td>
</tr>
<tr>
<td>2 btripod</td>
<td>17.0</td>
<td>7 cmooring--c4</td>
<td>10.3</td>
</tr>
<tr>
<td>3 cmooring--s4</td>
<td>2.5</td>
<td>8 cmooring--c5</td>
<td>12.3</td>
</tr>
<tr>
<td>4 cmooring--c5</td>
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<tr>
<td>5 adcpmooring</td>
<td>15.0</td>
<td>10 dtripod</td>
<td>20.0</td>
</tr>
<tr>
<td>6 dmooring</td>
<td>19.5</td>
<td>11 etripod--top</td>
<td>1.0</td>
</tr>
<tr>
<td>7 fmooring--bot</td>
<td>8.4</td>
<td>12 etripod--bottom</td>
<td>7.7</td>
</tr>
<tr>
<td></td>
<td></td>
<td>13 ftripod--top</td>
<td>1.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>14 ftripod--bottom</td>
<td>8.0</td>
</tr>
</tbody>
</table>

ADCP velocity data are stored in adcp2hour.mat.
The variables urn and vrm represent along-channel (up-channel) and cross-channel flow (toward New Jersey), respectively, and are in meters/second. The heights of the fifteen bins are 1.5 to 15.5 at 1 meter intervals. Zeit is the day of the year (EDT), and is identical to 'jd' (hudmix_m.mat).
D. SHIPBOARD DATA
Shipboard data are stored as hud95NN.mat, where NN is the survey day number (3-25) as given in Table 3.

Description of the variables in the shipboard data files:

varname - name of file

jd       - day of year (0.5 is noon on 1/1) (EDT)
hour     - local time (EDT)
lat, lon  - latitude, longitude (decimal degrees)
y        - along channel position in km from the Battery, where river joins New York Harbor
x        - across channel position in km the New Jersey Shore
z        - depth in meters, z=0 at water surface

depth    - Bottom depth calculated using depth at which ctd touched bottom

s        - Salinity in psu
t        - Temperature in degrees Celsius
conc     - Sediment concentrations in mg/L, OBS data converted using sed_conc.m
u        - velocity in cm/s, positive in flood (obtained by interpolating adcp data and rotating data into direction of maximum variance using rotate.m)

thetarot - degrees u rotated in counterclockwise direction, based on E 1st, N 2nd

Variable names for day 7 and 9:

linenum - line number (every line has three along channel transects)
xpos    - defines transect, 1=NJ side, 2= middle, 3=NY side

Variable names for day 10:

linenum - line number (every transect identified with a separate line number)
transect - index, across channel transects= 1, along channel transects= 2

Variable names for day 11:

linenum - line number (each line number has across and along channel transect)
transect - index, across channel transects= 1, along channel transects= 2
The success of the HUMIX project can be contributed to a great many people. The authors would like to express their appreciation to:

Harum Peters (SUNY, Stony Brook) and Gail Kineke (WHOI), for their collaboration;

Don Peters, for the development and oversight of construction of the quadrapod;

Craig Marquette, for the tripod assembly and shipboard surveys and tripod deployments;

Naomi Fraenkel and Todd Morrison, for their assistance in assembly of the quadrapod and its deployment;

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Captain Bret Zielenski, Roy Cash and Mark Wiggins of the R/V Onrust from SUNY Stony Brook, for their capable operations and assistance; and

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SECTION VIII

REFERENCES


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FRANCE
A field study was performed in the lower Hudson River, a partially mixed estuary with a relatively simple geometry (Figure 1), between August and October of 1995. The objectives of the study were (1) to quantify and characterize the turbulent transport of momentum and salt, and (2) to relate the turbulent transport processes to the local and estuar-wide dynamics.

The measurement program consisted of fixed and shipboard components. At a central site, a moored array of temperature-conductivity sensors and optical backscatter sensors (OBS), a bottom-mounted acoustic Doppler current profiler (ADCP), and a bottom-mounted array of acoustic travel-time current sensors (BASS), temperature-conductivity sensors, and OBS sensors resolved the vertical structure of velocity, salinity and turbidity and the near-bottom turbulence structure. Moored and bottom-mounted velocity, temperature, conductivity and pressure sensors at five secondary sites quantified the spatial and temporal variability of velocity, salinity and bottom pressure. Shipboard measurements with an ADCP and a conductivity-temperature-depth (CTD) profiler, accompanied by an OBS sensor, resolved the spatial structure and tidal variability of velocity, salinity and turbidity along several cross-channel and along-channel transects.

This report describes the measurements in detail. Section II describes the instrumentation, Section III describes the deployment and sampling schemes, Section IV describes the data processing, and Section V is a summary of plots of selected data. Section VI documents the data files and Sections VII and VIII give acknowledgments and references.

17. Document Analysis
   a. Descriptors
      stress
      salt flux
      mixed estuary
   
   b. Identifiers/Open-Ended Terms

   c. COSATI Field/Group

18. Availability Statement
   Approved for public release; distribution unlimited.