

1 Instruments and methods

2
3 A dual sensor device to estimate fluid flow velocity at diffuse hydrothermal vents

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14
15 **Abstract**

16 Numerous attempts have been made over the last thirty years to estimate fluid flow
17 rates at hydrothermal vents, either at the exit of black smoker chimneys or within
18 diffuse flow areas. In this study, we combine two methods to accurately estimate fluid
19 flow velocities at diffuse flow areas. While the first method uses a hot film
20 anemometer that performs high frequency measurements, the second allows a
21 relatively rapid assessment of fluid flow velocity through video imagery and provides
22 *in situ* data to calibrate the sensor. Measurements of flow velocities on hydrothermal
23 diffuse flow areas were obtained on the Mid-Atlantic Ridge (MAR). They range from
24 1.1 to 4.9 mm/sec., at the substratum level, in low temperature (4.5 to 16.4°C) diffuse
25 flow areas from the Tour Eiffel sulfide edifice. A strong correlation was observed
26 between fluid flow velocities and temperature, supporting the possible use of
27 temperature as a proxy to estimate flow rates in diffuse flow areas where such a
28 simple linear flow/temperature relation is shown to dominate.

29
30 **Keywords**

31 Fluid flow velocity, hydrothermal vent, hot film anemometer, video imagery, diffuse
32 flow

36 **1. Introduction**

37 High-temperature hydrothermal edifices at seafloor vent fields are particularly
38 complex and dynamic, offering to organisms a variety of potential habitats that range
39 from diffuse flow at near-ambient temperature to vigorously-venting hot smoker fluids.
40 Fluid composition and rates of fluid flow exiting at the chimney surface vary on the
41 same sulfide edifice, resulting in a complex mosaic of environmental conditions
42 available for organism colonization. The distribution of vent organisms is restricted to
43 regions where hydrothermal fluid interacts with seawater, providing both reduced and
44 oxygenated compounds essential to microbial primary producers (Jannasch and
45 Mottl, 1985; Childress and Fisher, 1992). The extreme dependence of vent
46 organisms on hydrothermal fluid supply (Desbruyères et al., 1985; Tunnicliffe et al.,
47 1990) and, conversely, the relative toxicity of these fluids (Somero et al., 1989)
48 support a close link between the distribution of vent faunal assemblages and the
49 characteristics of the fluids (Van Dover, 1990; Sarrazin et al., 1997; Shank et al.,
50 1998). Most evident is a trade-off between a nutritional dependence and tolerance to
51 harsh conditions (Chevaldonné, 2000; Shillito et al., 2001; Lee, 2003; Ravaux et al.,
52 2003; Cosson et al., 2008).

53 Physico-chemical measurements of temperature, pH, and concentrations of sulfide,
54 methane and metals have been proposed to influence the spatio-temporal
55 distribution of hydrothermal fauna (Johnson and Tunnicliffe, 1985; Johnson et al.,
56 1986, 1988a,b; 1994; Fisher et al., 1988a,b; Chevaldonné et al., 1991; Shank et al.,
57 1998; Sarrazin et al., 1999; Desbruyères et al., 2001; Luther et al., 2001; Urcuyo et
58 al., 2003; Sarradin et al., 2008). Moreover, some authors have suggested that
59 microhabitat variation in hydrothermal fluid flux may have an important influence on
60 colonization by vent species (Desbruyères et al., 2000; Mullineaux et al., 2003) and
61 also on species distribution (Sarrazin et al., 1999). Gradients of hydrothermal fluid
62 flux may even influence successional processes at deep-sea vents (Sarrazin et al.,
63 1997; Sarrazin et al., 1999; Sarrazin et al., 2002; Mullineaux et al., 2003).

64 Nevertheless, only a few attempts of quantitative fluid flow-rate measurement at the
65 scales of vent faunal assemblages have been made (Schultz et al., 1992, 1996;
66 Ramondenc et al., 2006). The majority of efforts have concentrated on discrete high -
67 temperature hydrothermal discharges or on large diffuse-flow areas on the seafloor to
68 estimate large-scale heat flow output (Corliss et al., 1979; Converse et al., 1984;

69 Rona and Trivett, 1992; Schultz et al., 1992, 1996; Baker and Cannon, 1993; Ginster
70 et al., 1994; Trivett and Williams, 1994; Lavelle et al., 2001; Pruis and Johnson,
71 2004; Ramondenc et al., 2006).

72 A number of different methods have been used since the discovery of vents, starting
73 with visual observations using a vane-type flow meter from the Alvin submersible
74 (Corliss et al., 1979). Later on, turbine flow meters combined with temperature-probe
75 data allowed the measurement of fluid flow velocities exiting from high-temperature
76 vents (Converse et al., 1984; Ginster et al., 1994). After calibration in the laboratory,
77 the turbine flow meter was held 3 cm above the fluid exit to limit jamming of the
78 turbine by small particles and to prevent melting of the plastic insulation.
79 Measurements at diffuse-flow areas include those of Schultz et al. (1992); they
80 obtained a 45-day time-series of flow rate on a diffuse flow area colonized by
81 siboglinid tubeworms using an electromagnetic-induction flow meter that was
82 calibrated *in situ* during the descent of the submersible. A later design, the MEDUSA
83 device, was developed by Schultz et al. (1996). It measures temperature and velocity
84 of hydrothermal effluents by means of a titanium rotor, whose spin rate is detected
85 optically. However, it was shown that the sensor was significantly affected by fouling
86 during long-term deployment. An alternative method, visual tracking of particles and
87 eddies in the ascending fluids, was used by Rona and Trivett (1992) and Ramondenc
88 et al. (2006). Both used a graduated rod placed above the vent orifice. Fluid velocity
89 was estimated through video imagery which requires the presence of eddies and
90 particles and does not allow for autonomous long-term measurements.

91 Measurement of fluid flow rate is also a challenge in cold-seep studies. As flow rates
92 are lower and environmental constraints lighter, the sensors are based on different
93 principles. For example, Linke et al. (1994) initially used a mechanical mass-flow
94 meter (Bernoulli type) calibrated as a function of temperature, pressure and salinity.
95 The sensor was subsequently replaced by a thermistor flow meter that can measure
96 velocities from 0.01 to 50 cm s⁻¹. Tryon et al. (2001) used a chemical and aqueous
97 transport meter measuring the degree of dilution of a chemical tracer injected by an
98 osmotic pump at a known rate. This device is capable of measuring a serial record of
99 flow rates through the sediment surface up to 15 m yr⁻¹.

100 The major objective of our study was to build a reliable tool to measure fluid flow
101 velocities on small-scale hydrothermal diffuse flow areas. We have developed a dual
102 sensor approach to overcome harsh environmental constraints and to allow in-situ

103 calibration. Fluid flow velocities were obtained by combining hot film anemometer
104 measurements with visual estimates of particle ascent through video imagery. The
105 first results using this dual sensor, obtained at the Lucky Strike vent field at 37°17'N
106 on the Mid-Atlantic Ridge (MAR), are presented.

107 **2. Materials and methods**

108 **2.1. Fluid flow devices**

109 **a. The Flow Visualizer**

110 A new instrument, designed at Ifremer with the help of the Remotely Operated
111 Vehicle (ROV) *Jason* engineers (Woods Hole Oceanographic Institution 1998), was
112 developed to estimate fluid flow velocity. This “Flow Visualizer” is composed of a
113 transparent, 2-cm interval graduated pipe mounted on a large cylindrical chamber
114 (300 mm Internal Diameter; Figure 1). Flow rate is determined by placing the device
115 on selected diffuse-flow areas and by measuring particle ascent velocity within the
116 pipe using video imagery. Individual particles are located by the observer, and their
117 ascending time is recorded using the time code available on the video. Their travel
118 distance is evaluated by using the 2-cm-spaced graduations of the pipe. The
119 observer records the time that it takes for each visible particle to reach the top of the
120 cylinder.

121 The variability due to the observer was examined with two Wilcoxon signed ranked
122 tests for paired samples (Table 1). Because several particles are regularly passing
123 through the graduated tube, each observer does not necessarily select the same
124 ones. The first test was done to evaluate difference in the mean velocity measured by
125 two observers between different video sequences, regardless of the particles chosen.
126 The second was done to assess difference in the measured velocity for common
127 particles between two observers. The specific particles every observer measured
128 were identified by noting the time each particle entered the flow tube. This was done
129 for three paired data sets (OBS1 vs. OBS2, OBS1 vs. OBS3 and OBS2 vs. OBS3),
130 testing three different observers.

131

132 **b. The flow sensor**

133 The heated thin film flow sensor used (Figure 2) was delivered by Earth-Ocean
134 Systems Ltd. The sensor is a Constant Voltage Anemometer type (CVA). This device
135 employs two thin-film Pt resistive temperature sensors and a precision surface-mount
136 resistor used as a heating element, contained within a paddle made of epoxy. The
137 voltage applied to the heating element is constant. The sensor is immersed in the
138 hydrothermal effluent. The upstream temperature sensor measures the ambient
139 temperature (T_a), whereas the second, coupled thermally to the heater, measures
140 the hot film temperature (T_w). The difference between T_a and T_w is proportional to
141 the effluent flow rate, reflecting the increasing quantity of heat advected away from
142 the thermal sensors in proportion to the increasing flow rate of the effluent.

143

144 **c. Dual system –The FLO**

145 The Flow Visualizer and the flow sensor were combined in a single instrument,
146 named FLO, to perform a cross-comparison of the two methods. The dual system is
147 composed of a transparent 2-cm graduated tube mounted on a chamber (Figure 1). A
148 honeycomb material consisting of cells that are 3 mm in diameter was placed inside
149 the chamber to regularize the flow regime. The flow sensor was set at the base of the
150 tube in an elliptical nozzle. A flexible rubber skirt was used to seal the bottom of the
151 chamber and limit leakage when the instrument was deployed on irregular surfaces.
152 The size and shape of all of the elements composing the FLO were determined
153 according to hydrodynamic constraints. The objective was to obtain a laminar (no
154 turbulence) and uniform (flat velocity profile) flow at the sensor level. First of all, the
155 pipe inner diameter (50 mm) was determined by the sensor size. To avoid
156 disturbance at the measurement level, the length of the pipe was set at 500 mm to
157 reach 10 times the inner diameter. The nozzle, mounted between the pipe and the
158 chamber, insures a flat velocity profile. The ratio between the diameter of the
159 chamber and that of the pipe (6:1) was calculated to amplify the velocity values
160 obtained by the sensor (sensitivity gain). Therefore, to obtain the velocities at the
161 substratum level, the results have to be divided by 37.6. The honeycomb layer was
162 placed at 150 mm, which corresponds to half the chamber diameter, to insure a
163 homogeneous flow at the nozzle inlet (Figure 1). The honeycomb should not have

164 any hydrodynamic influence except for regulating the flow. The data-logger and
 165 battery are included in a titanium housing, rated up to 6000 m.
 166 The FLO is deployed by the manipulator arm of a ROV on a targeted sampling area
 167 (Figure 3). The instrument must be placed on a relatively flat surface, and the pipe
 168 has to be vertical (more or less 10°). Once the instrument is set, the ROV main
 169 camera is focused and video imagery of the fluids ascending through the pipe is
 170 recorded for a few minutes. The sampling time was optimized to 10 minutes per
 171 sampling area for the MoMARETO cruise (2006). The FLO can work autonomously
 172 for up to 24 hours.

173 **2.2. Modeling the sensor response**

174 To characterize the relationship between fluid flow velocity (U), fluid temperature (Ta)
 175 and the hot film temperature (Tw), the formula of a Constant Voltage Anemometer
 176 (CVA) (King 1914) is used.

177 (eq. 1)
$$f(U) = A + B \cdot U^n$$

178 Where U is flow velocity, and A, B and n are constants.

179 The PDR method, ratio of Power dissipated in hot-wire to the Difference in the
 180 Resistance (Sarma & Comte-Bellot, 2002; Truzzi et al. 2002) states that:

181 (eq. 2)
$$\frac{P_w}{(R_w - R_a)} = A + B \cdot U^n \quad \text{with: } P_w = \frac{E_w^2}{R_w}$$

182 where Pw is the power dissipated in the heating element, Ew is the constant voltage
 183 applied to the hot-wire, Rw is the resistance of the heating element and Ra is the
 184 resistance in ambient conditions. The two equations become:

185 (eq. 3a)
$$U^n = \left(\frac{E_w^2}{B} \right) \cdot \frac{R_w^{-1}}{R_w - R_a} - \left(\frac{A}{B} \right)$$

186 Since the sensor resistances are temperature dependent, the wire temperature T_w
 187 and the fluid temperature T_a are implicitly represented through R_w and R_a . The other
 188 terms of the formula are constants, so we may set $C = E_w^2/B$ and $D = -A/B$. Then
 189 equation 3a can be written as:

190 (eq. 3b)
$$U^n = C \cdot \frac{T_w^{-1}}{T_w - T_a} + D$$

191 This theoretical equation was empirically transformed to better match the sensor
 192 response obtained in our experimental design. Therefore, the best curve fit is
 193 obtained with $n=1$ and by applying a power law (m) to the ratio of T_w over the
 194 temperature compensation term ($T_w - T_a$). With these modifications, the response
 195 model of our sensor becomes:

196 (eq. 4)
$$U = C' \cdot \frac{T_w}{(T_w - T_a)^m} + D'$$

197 with C' , D' and m as calibration constants.

198 In order to find these calibration constants, we used a specifically designed
 199 calibration device (an upside down version of the FLO; Figure 4). The calibration
 200 device uses Bernoulli & Torricelli gravity principles. It consists of a plane-parallel
 201 water tank regulated at a constant level by an overflow pipe (Figure 4). The flow
 202 sensor is inserted at the entrance of the outlet pipe. The flow is calmed upstream of
 203 the sensor by a honeycomb structure and regulated downstream by a needle valve.
 204 The geometry of the calibration device has been calculated to limit hydrodynamic
 205 disturbances as for the FLO instrument. The flow rate is calculated by recovering and
 206 weighing the water passing through the system during a measured period. The
 207 velocity is then deduced by dividing the flow rate by the cross sectional area at the
 208 sensor level. Temperatures are obtained by the calibrated flow sensors. A series of
 209 regulated ambient temperatures (T_a : 17.5 to 35.3°C) and flow velocities (18 mm s⁻¹ to
 210 160 mm s⁻¹) were used to obtain the different response curves (Figure 5). The
 211 coefficients C' , D' and m , which are sensor-specific, are estimated using the
 212 Marquardt non-linear regression method (Statgraphics Plus software© version 5.1).
 213 For the sensor used to generate the response curves in Figure 5, we found:

214 (eq. 5)
$$U = 875.712 \cdot \frac{T_w}{(T_w - T_a)^{3.24614}} - 3.84287$$

215 This equation describes the curves seen in Figure 5 and the results from the
 216 calibration give the data shown in Figure 6. Calibration coefficients can also be

217 determined in the field, using velocity measurements from video imagery as a
218 reference.

219 **2.3. At-sea trials**

220 The first in-situ use of the FLO was carried out during the EXOMAR cruise on the RV
221 L'Atalante with the ROV *Victor6000* (2005) on the Tour Eiffel edifice located within
222 the Lucky Strike vent field on the Mid-Atlantic Ridge. Four trials were done allowing
223 validation of the system deployment by the ROV, refinement of the method, and the
224 acquisition of two series of data using the visual approach only (because of failure of
225 the sensor).

226

227 The second use of the FLO, with a new sensor that was calibrated in the field, was
228 during the MoMARETO cruise (R/V *Pourquoi pas?*/ROV *Victor6000*, Sarrazin et al.,
229 2006). The system was deployed during four dives on the same sulfide edifice
230 (Figure 3). In addition to the temperature taken by the flow sensor (Ta), ambient
231 seawater temperature measurements were acquired with the ROV's temperature
232 probe and with autonomous probes (NKE®, France). All data sets (video,
233 temperature) were synchronized with the *Victor6000* internal clock.

234

235 **3. Results**

236 **3.1 Observer effect**

237 Six to nine video sequences from three dives were analyzed. Results of the first
238 Wilcoxon test show that the mean velocity estimates from OBS3 was statistically
239 different from that of the two others when using all data available (Table 1). Results
240 of the second Wilcoxon test for particle velocities showed that no statistical difference
241 between the three observers is observed when using the same particles (Table 1).
242 These results validated the robustness of the visual method to evaluate particle
243 speed regardless of the observer. The differences observed in the first test were
244 probably due to difference in particle selection between the three observers. An
245 optimal protocol would take the mean of velocity estimates obtained by two or more
246 observers, regardless of the particles they choose. This will lead to better estimates
247 of the fluid velocities observed in the field.

248

249 **3.2 Data acquisition and sensor post-calibration**

250 Fourteen data sets, coupling sensor measurements and video imagery, were
251 obtained and processed. The two temperature probes (T_a and T_w) were calibrated on
252 board. The data were acquired every five seconds. The duration of a measurement,
253 gathering both video and sensor data, varied from 0.5 to 10 minutes per sampling
254 site. No leakage was observed at the base of the FLO skirt during these
255 measurements. Unfortunately, the video images were only usable for 8 of 14
256 deployments. On the other sequences, the amount of particles was insufficient to
257 obtain reliable data. In addition, sensor data were lost because of power failure
258 during dive 305.

259 The calibration of the new sensor was done using the velocity measurements from
260 video imagery as reference. The coefficients of equation 4 for the new sensor,
261 calibrated in the field, were found by combining ambient temperature (T_a), hot film
262 temperature (T_w) and fluid flow velocity estimated from video imagery. The mean
263 temperature values (T_a and T_w) were calculated from the stabilized part of the
264 sequence (see example in Figure 7). The resulting equation, giving the flow velocity
265 U , measured by the flow sensor becomes:

266 (eq. 6)
$$U = 16.3399 \cdot \frac{T_w}{(T_w - T_a)^{0.230206}} - 60.5588$$

267 The differences in calibration coefficients (equations 5 and 6) are due to the use of
268 two slightly different sensors.

269 The sensor flow velocity was calculated for all data sets, including the deployments
270 where no video was available (Table 2). The flow rate was deduced from the sensor
271 flow velocity using the internal dimensions of the FLO structure (30 cm skirt diameter
272 and thus 706.9 cm² area at the base of the FLO structure and 18.8 cm² free section
273 at sensor level).

274

275 **3.3 Temperature and velocity data**

276 The ambient temperature (T_a) measured in the diffuse flow areas ranges between 4.5
277 and 16.4°C for a surrounding seawater temperature of 4.4°C. The hot film
278 temperature (T_w) varied from 8.7 to 20.0°C. The flow velocities extracted from video
279 analyses and used for calibration varied from 56.8 to 161.5 mm s⁻¹, and the

280 calculated flow velocities, extracted from the sensor data, varied from 41.9 to 183.6
281 mm s⁻¹ at the sensor level and from 1.1 to 4.9 mm s⁻¹ at the substratum level (Table
282 1). The calculated flow rates extend from 66.2 to 293 L min⁻¹ m⁻². Figure 7 gives an
283 example of the fluid velocity data obtained during the fourth deployment of dive 304.

284

285 **4. Discussion/conclusion**

286 Within hydrothermal vent fields, the distribution of faunal assemblages may be
287 influenced significantly by small-scale variations in fluid flow (Schultz et al., 1992;
288 Sarrazin and Juniper, 1999). In this study, we combine two methods to accurately
289 estimate fluid flow rates on diffuse flow areas. The first uses a heat-flow sensor, and
290 the second measures fluid flow rates with visual estimates of particle ascent through
291 video imagery. They are complementary: whereas the visual technique allows a
292 relatively rapid assessment of fluid flow velocity, the flow sensor performs high-
293 frequency measurements and provides temperature data. Nevertheless, the use of
294 this sensor is sensitive to environmental temperature changes because its principle is
295 based on temperature measurements. The dual approach is a convenient means to
296 overcome this limitation by using video imagery to acquire discrete fluid-velocity
297 estimates for post-calibration.

298 The dual approach used in this study allowed us to gather reliable measurements of
299 flow velocities on a hydrothermal edifice on the mid-Atlantic ridge. Comparisons with
300 other studies remain difficult because the measurement methods vary (direct versus
301 indirect) and only a few measurements consider the surface studied (Table 3).
302 Ideally, to be comparable, fluid velocity and fluid flow rate data should take the
303 surface into account and include a detailed description of the type of fluid emissions
304 (discrete versus diffuse).

305 Our measured flow velocities (at the sensor level) fall within the ranges observed by
306 Rona and Trivett (1992) and Ramondenc et al. (2006) at low-temperature diffuse
307 venting sites (Table 3). Nevertheless, these data do not inform about the emissions
308 at the substratum level, reflecting the conditions experienced by the fauna. Data at
309 the substratum level are scarce. Those obtained by Schultz et al. (1996) in a single
310 diffuse flow site at TAG (Mid-Atlantic Ridge) give a particularly weak fluid velocity for
311 a quite constant temperature (Table 3). The discrete velocity data obtained within this

312 study at the substratum level are comparable. Nevertheless, they differ greatly from
313 those found in diffuse flow sites from the Juan de Fuca Ridge (Schultz et al. 1992),
314 highlighting the heterogeneity of the vent environments. Moreover, measured flow
315 rates from high-temperature exits can be up to 30 times higher than flow rates
316 obtained in diffuse flow sites (Table 3).

317

318 One notable result of this study is the strong linear relationship between the ambient
319 temperature and the flow rate in low-temperature areas (4.7-16.4°C, Figure 8). This
320 correlation is in accordance with the buoyant plume theory mentioned by Schultz et
321 al. (1992) for sites where diffuse hydrothermal fluids are of shallow, near-seafloor
322 origin. According to this theory, the flow dynamics of such fluids should be governed
323 primarily by the buoyancy of hot fluids rather than by poroelastic Darcy flow.
324 Additional measurements are now required to corroborate the data acquired during
325 this study and to refine the relationship between fluid flow velocity and temperature
326 over a larger range and at variable tide cycles.

327 In areas where the relationship between temperature and flow velocity is verified,
328 temperature can be used as a proxy to estimate fluid flow rates within different faunal
329 assemblages. Thus, not only temperature may be used as a key-parameter to
330 estimate the chemical composition of the fluids (Sarradin et al., 2008) but also other
331 factors linked to fluid flow rates that could be of ecological significance. Nevertheless,
332 while the FLO may be useful for measuring fluid flow rate in most hydrothermal
333 communities (alvinellid, gastropod and mussel assemblages), it would require a
334 major adaptation to measure fluid flow in long tube worm communities. Ultimately,
335 the energy budget required to sustain chemosynthetic processes within different
336 faunal assemblages could be estimated through extrapolation of discrete flow-rate
337 measurements (Martins et al., 2008).

338

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495

496 **Figure captions**

497

498 **Figure 1.** The flow visualizer is composed of a transparent, 2-cm interval graduated
499 pipe mounted on a large cylindrical chamber.

500 **Figure 2.** The flow sensor is constituted of two Pt resistive temperature sensors and
501 a hot wire embedded in an epoxy paddle. Earth-Ocean Systems Ltd.

502 **Figure 3.** The dual system FLO was deployed on the Tour Eiffel hydrothermal edifice
503 during the MoMARETO cruise in 2006. The flow rate is determined by a dual
504 approach combining video imagery and flow sensor measurements.

505 **Figure 4.** Scheme of the flow sensor calibration device.

506 **Figure 5.** Applied fluid flow velocity versus hot film temperature (T_w) obtained with
507 the flow sensor probes in the laboratory at different ambient temperatures (T_a : 17.5
508 to 35.3°C).

509 **Figure 6.** Calculated flow velocity (U) versus real flow speed, measured in the
510 laboratory, using the calibration model (eq. 5). The determination coefficient R^2 is
511 0.988.

512 **Figure 7.** Fluid velocity data obtained during the fourth deployment of dive 304
513 during the MoMARETO cruise in 2006. The white rectangles (\square) represent the flow
514 velocities as measured by Observer 2 (OBS2) using video image analyses. To get
515 the best “mean” possible and to limit large standard deviations, only the velocity
516 values on the stable portion of the curve (\blacksquare) were used to calculate the different
517 coefficients. The bold line represents the interval used to calculate the final mean
518 sensor flow velocity.

519 **Figure 8.** Mean flow velocity versus mean ambient flow temperature (T_a) as resulted
520 from the 14 measurements on the Eiffel Tower edifice. The determination coefficient
521 R^2 is 0.999 for a total number of measurements (n) of 14. The following equation:
522 Velocity = 11.566 T_a - 7.8433 where T_a is the ambient flow temperature (°C)
523 describes a best fit to the velocity data.

524

525

526 **Tables**

527

528 Table 1. Paired comparisons of fluid flow velocities as measured by three different observers
 529 for 6-9 different video sequences. Test 1: Wilcoxon signed rank test for difference in the
 530 mean velocity for all particles, in all paired sequences between observers. Test 2: Wilcoxon
 531 signed rank test for difference in the velocity for paired particles between observers. V and p-
 532 values are given. * indicates that there is a statistical difference ($\alpha = 0.05$) between two
 533 observers.

Wilcoxon signed rank test	OBS1	OBS2	OBS1	OBS3	OBS2	OBS3
Test 1						
n sequences	9		6		6	
V	15		0		0	
P-values	0.4258		0.03125*		0.03125*	
Test 2						
n particles	104		93		37	
V	1725.5		1216.5		296	
P-values	0.1077		0.8814		0.3519	

534

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536

537 Table 2. Temperature and flow measurements acquired during three dives of the
 538 MoMARETO cruise. The approximate duration of each sequence is given. The **video**
 539 **flow velocity** was extracted from video image analyses. *T_a* and *T_w* are respectively
 540 the ambient and the hot film temperature measured by the flow sensor. The **flow**
 541 **velocity at the sensor level** is obtained using equation 6. The mean **flow velocity**
 542 **at the substratum level** was estimated by dividing the velocity at the sensor level by
 543 37.6 (representing the ratio between the surface area of the chamber (706.9 cm²)
 544 and that of the pipe (18.8 cm²). The **flow rate** is directly calculated by multiplying the
 545 sensor flow velocity with the cross-sectional area at the sensor level divided by the
 546 studied surface area: flow velocity_{sensor} (dm/min) x pipe surface area (dm²)/chamber
 547 surface area (m²). SD corresponds to standard deviation.

Dive	Duration (min ± 0.5 s)	Video flow velocity (mm s ⁻¹) ± SD	T _a (°C) ± SD	T _w (°C) ± SD	Flow velocity at the sensor level (mm s ⁻¹) ± SD	Mean flow velocity at the substratum level (mm s ⁻¹) ± SD	Flow rate (L min ⁻¹ m ⁻²) ± SD	
301	17	161.5 ± 12.5	15.0 ± 0.6	18.9 ± 0.5	164.8 ± 6.8	4.4 ± 0.2	262.9 ± 10.8	
	10		16.4 ± 0.3	20.0 ± 0.3	183.6 ± 4.5	4.9 ± 0.1	293.0 ± 7.1	
	2		4.7 ± 0.1	9.3 ± 0.2	46.6 ± 1.6	1.2 ± 0.1	74.3 ± 2.5	
	7		6.9 ± 0.2	11.4 ± 0.3	71.6 ± 2.6	1.9 ± 0.1	114.2 ± 4.1	
	6		151.9 ± 9.5	13.8 ± 0.5	17.5 ± 0.4	151.7 ± 5.9	4.0 ± 0.2	242.0 ± 9.4
302	8	61.1 ± 9.8	6.2 ± 0.2	11.0 ± 0.3	64.4 ± 2.9	1.7 ± 0.1	102.8 ± 4.6	
	10		4.5 ± 0.1	8.7 ± 0.3	41.9 ± 1.8	1.1 ± 0.1	66.2 ± 2.9	
	2.5		14.0 ± 0.6	17.9 ± 0.6	153.3 ± 6.7	4.1 ± 0.2	244.6 ± 10.7	
	2		6.6 ± 0.1	11.2 ± 0.1	68.8 ± 1.1	1.8 ± 0.1	109.8 ± 1.8	
304	10	67.7 ± 10.4	6.2 ± 0.2	10.6 ± 0.4	62.8 ± 3.2	1.7 ± 0.1	100.2 ± 5.1	
	0.5		64.2 ± 1.5	6.1 ± 0.2	11.3 ± 0.2	65.7 ± 2.0	1.7 ± 0.1	104.8 ± 3.1
	7		56.8 ± 6.2	5.9 ± 0.2	10.8 ± 0.3	62.0 ± 2.1	1.6 ± 0.1	99.0 ± 3.4
	8		77.9 ± 5.2	7.3 ± 0.1	12.1 ± 0.3	76.9 ± 1.8	2.0 ± 0.1	122.7 ± 2.8
	7.5		111.0 ± 3.7	9.7 ± 0.2	14.3 ± 0.2	104.1 ± 2.5	2.8 ± 0.1	166.0 ± 4.1

548

549 Table 3: Review of fluid flow velocities measured in different deep-sea
 550 chemosynthetic ecosystems. Modified from Ramondenc et al. (2006). * Equivalent to
 551 measurement at sensor level, not calibrated for surface or no information on
 552 calibration. **Equivalent to measurement at substratum level.

553

Authors	Sites	Type of emission	Methods	T °C	Flow velocity mm s ⁻¹	Flow rate
Corliss et al. 1979	Galapagos	Vents	Visual observation on a vane-type flowmeter			2-10 L s ^{-1*}
Converse et al. 1984	EPR 21°N	Hot vents and chimneys	Turbine flowmeter	275-350	700-2400*	150 kg H ₂ O s ⁻¹
Rona and Trivett, 1992	Juan de Fuca Ridge	Discrete sources	Visual, eddies and particles tracking	108-326	250-900*	
		Diffuse sources		21-226	50-100*	
Schultz et al. 1992	Juan de Fuca Ridge	Diffuse flow (tubeworms)	Electromagnetic induction flow meter, time series	7-13	70-150**	
Ginster et al. 1994	Juan de Fuca Ridge	Hot vents chimneys	Turbine flowmeter	296-374	600-6200	
				235-350	1300 – 3500	
Schultz et al. 1996	TAG Mid-Atlantic Ridge	Diffuse flow Time series	Medusa (titanium rotor velocity sensor)	14±0.5	5.1±0.4**	
Ramondenc et al. 2006	EPR 9°50' N	High temperature venting sites	Visual, eddies and particles tracking	345-388	100 – 300*	
		Low temperature diffuse venting sites		10	40*	
This study	LS- MAR	Low temperature diffuse venting sites	Visual and heated thin film flow sensor	4.7 – 16.4	42-184* 1.1-4.9**	66 – 293 L min⁻¹ m⁻²
Seeps						
Linke et al. 1994	Cascadia margin		Mechanical mass flow meter thermistor hot bead flowmeter		0.5 – 10 (measured by the sensor)	30 – 1065 m yr ⁻¹ (max 0.03 mm s ⁻¹)
Tryon et al. 2001	Cascadia margin		Chemical and aqueous transport meter		10 – 200 cm yr ⁻¹	

554

555

Figures

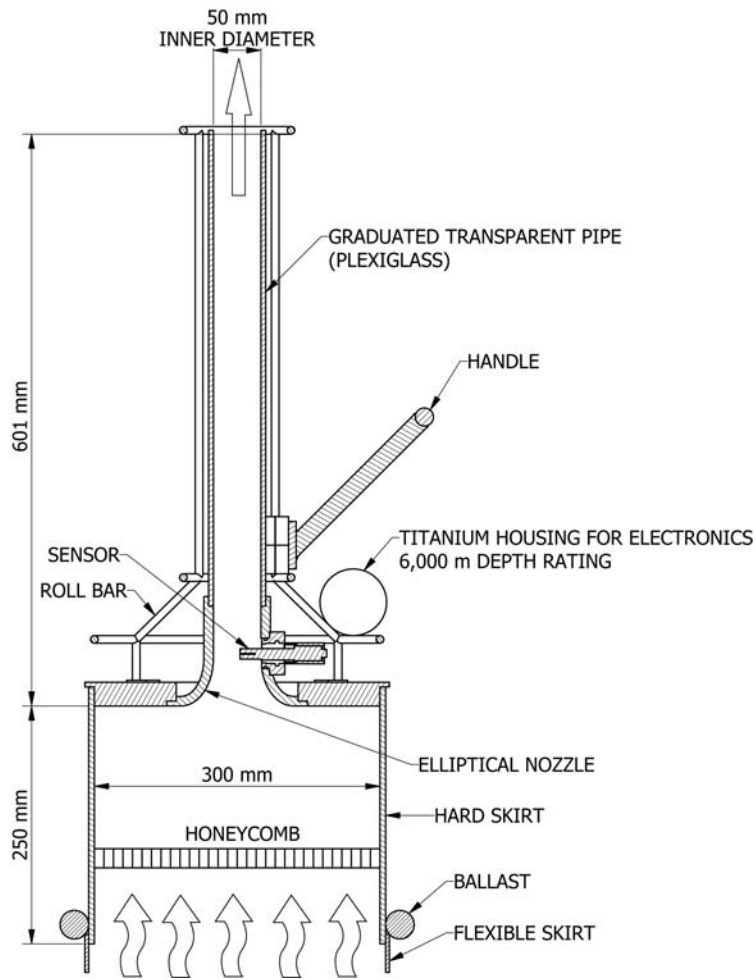


Figure 1

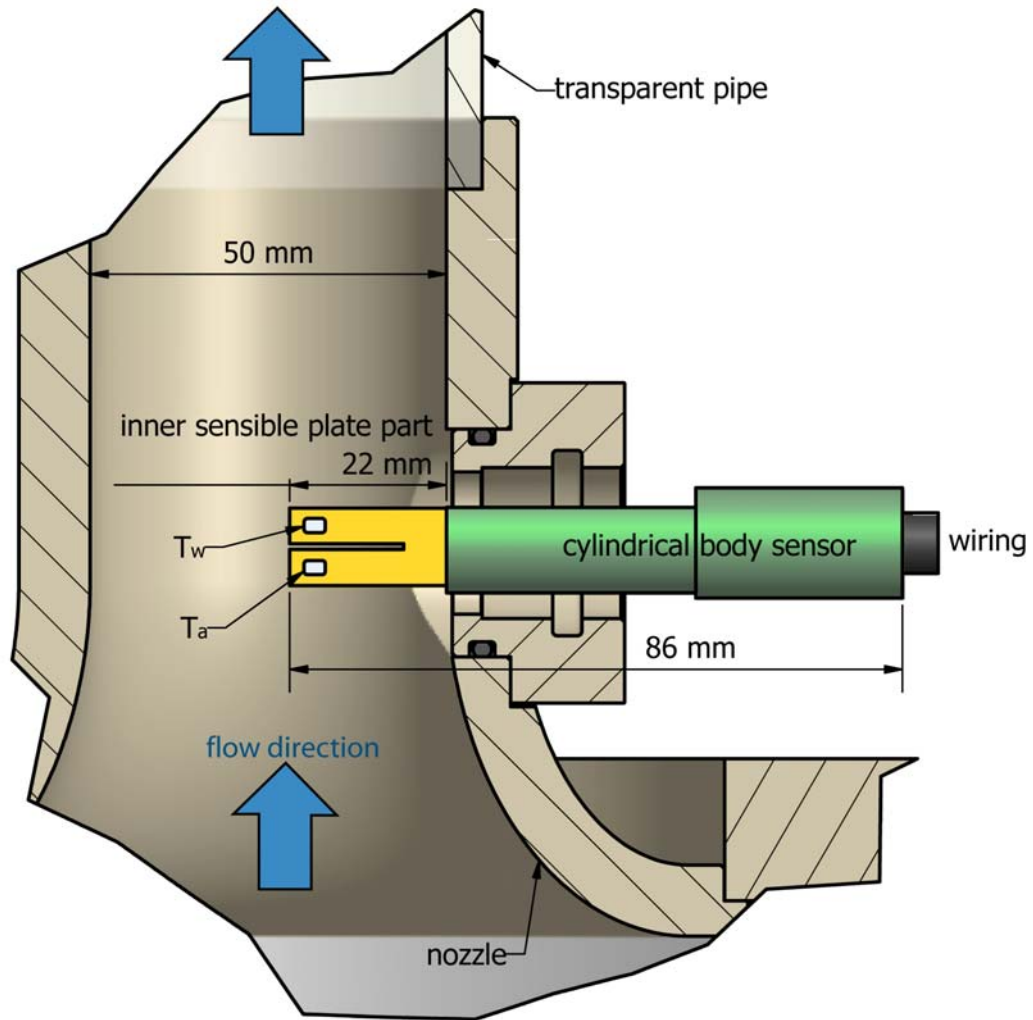


Figure 2.

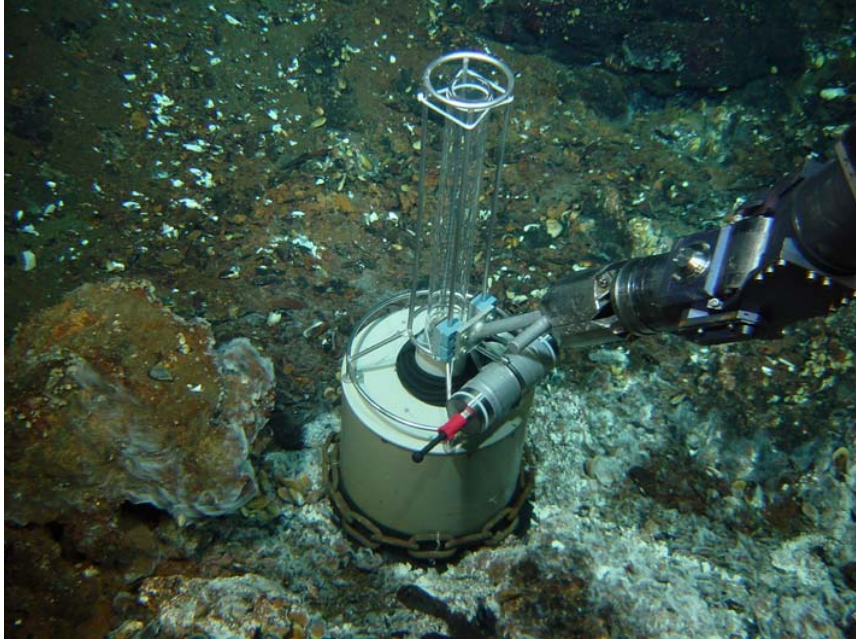


Figure 3.

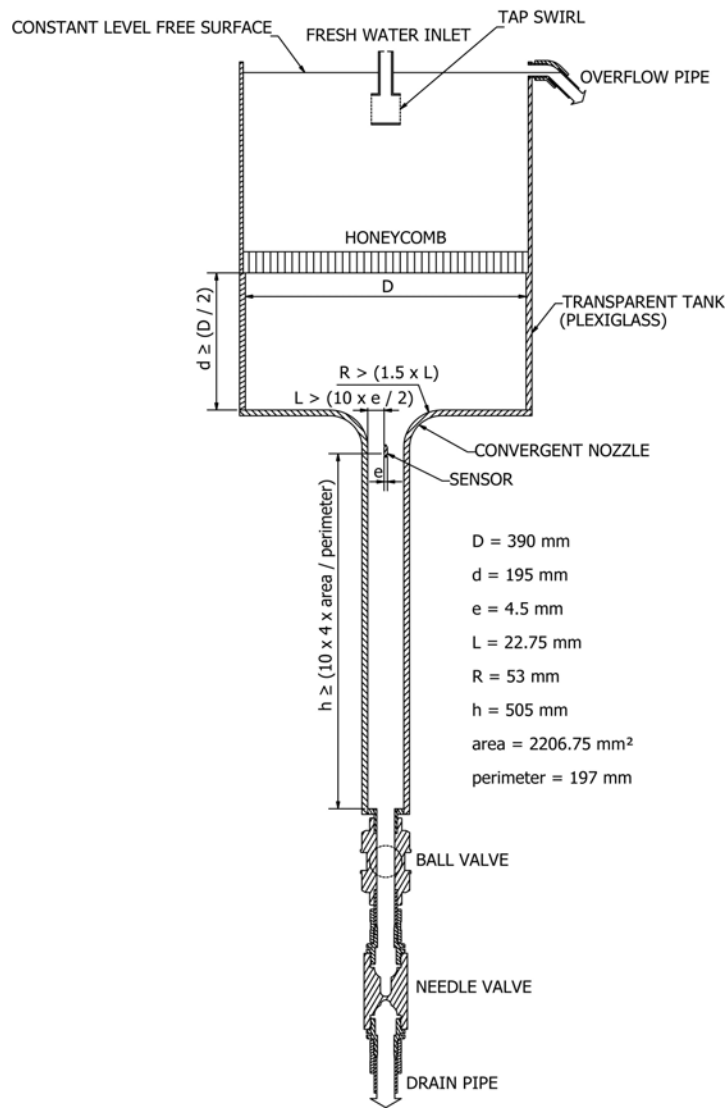


Figure 4.

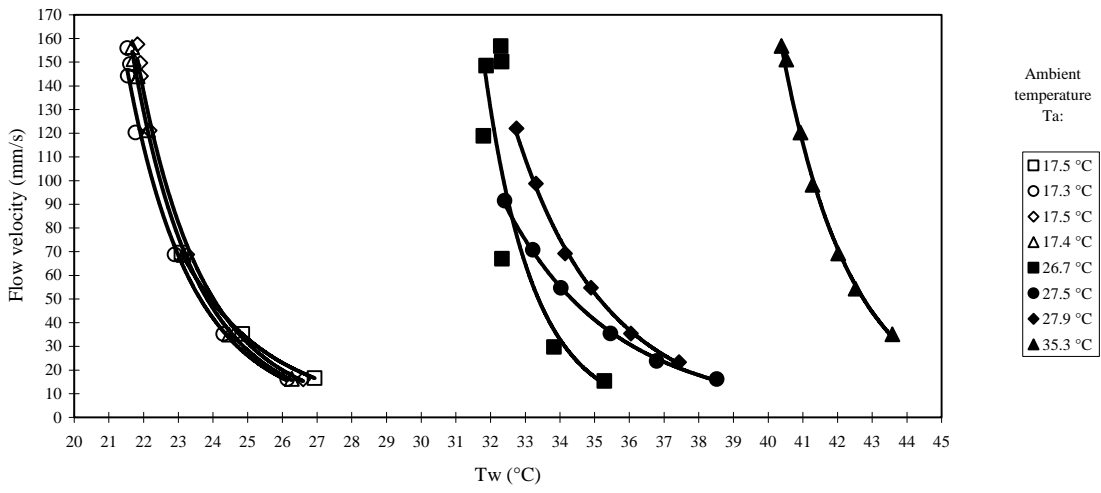


Figure 5.

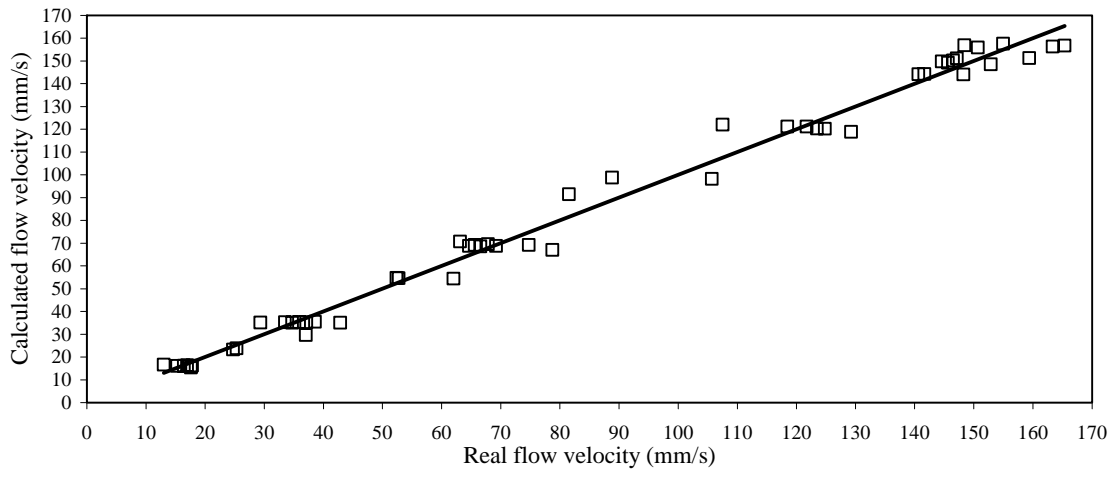


Figure 6.

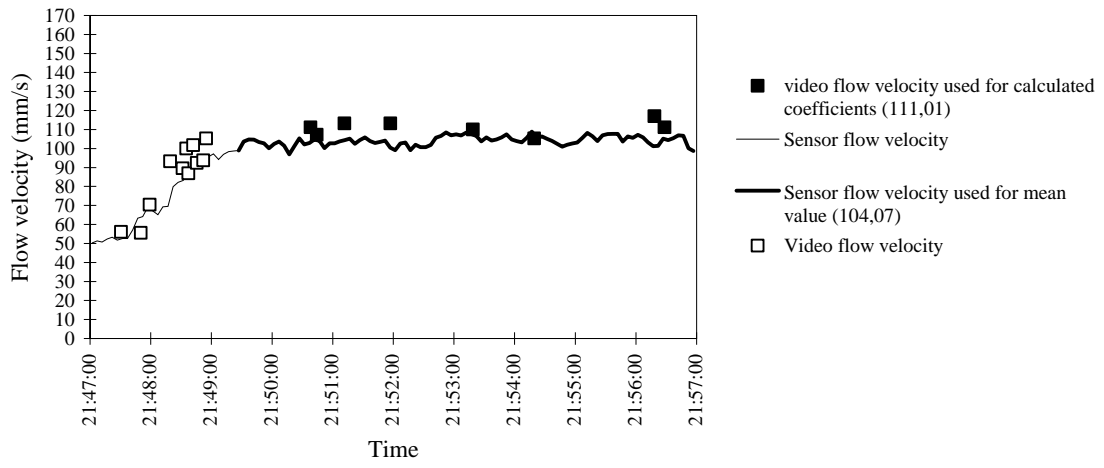


Figure 7.

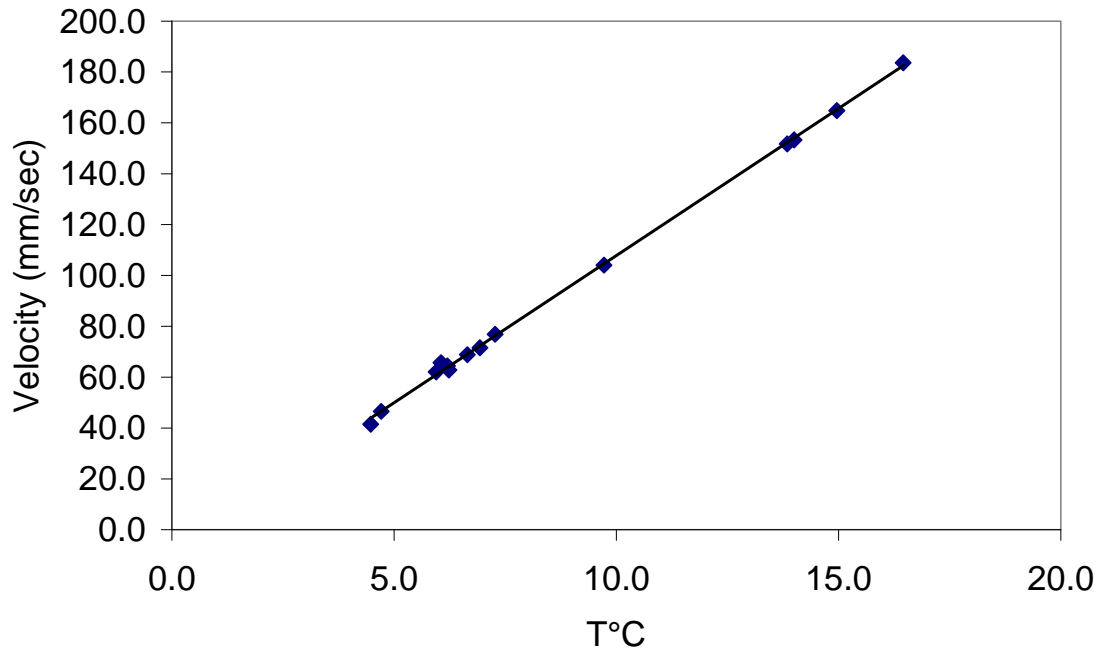


Figure 8.