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## Supplementary Information

### 2 **Coupled Model Biases Breed Spurious Low-frequency Variability in** 3 **the Tropical Pacific Ocean**

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17 **Table caption:**

18 Table S1: Type-1 and Type-2 ENSO models used in this study: Model names; institutes; ocean  
19 horizontal mean zonal resolution (at the equator in °E) × mean 25 °N-35 °N resolution in latitude  
20 (in °); atmospheric horizontal resolution (in E×N); No. of years; references. Please refer to the  
21 Table Appendix 9.A in IPCC WG1 AR5 Chapter 9 for the more information. We chose the same  
22 ensemble member from the CMIP5 pi-control runs, where only one run was available for CESM  
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25 **Figure caption:**

26 Figure S1: Examples of leading EOF mode (EOF1) of centennial-scale (80-300 years band pass  
27 filtered using a Lanczos filter) annual SST from pre-industrial control runs of different models.  
28 Models names and variability (in %) are mentioned in the title of each plot. EOFs are expressed in  
29 °C per standard deviation. Not all models show a dipole pattern and PCO may exist without a  
30 prominent dipole in EOF1 pattern. Therefore, detecting PCO in terms of a dipole pattern in EOF1  
31 of centennial-scale SST may not be appropriate.

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33 Figure S2: Standard deviation of annual unfiltered SST (in °C) for individual models from our  
34 study. Legends in each plot indicate the model name.

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36 Figure S3: Same as Figure S2, but for the remaining models from our study.

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38 Figure S4: Scatter plots between equatorial unfiltered DJF SST variability (data same as Figure.  
39 1a, in °C) at the reference longitude 164 °E (REF) with various longitudes. Each dot represents a  
40 model. We chose the reference point in the western Pacific because our argument is that the  
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42 everywhere or not) and related mean-state variability can be related to the emergence of centennial-  
43 scale variability over the western Pacific. The selected point in the western Pacific offers a clear  
44 separation between two types of models.

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46 Figure S5: Standard deviation of high frequency (10 years high pass filtered using Lanczos filter)  
47 annual latent heat flux (in  $\text{Wm}^{-2}$ ) for Type 1, Type 2 ENSO model and their difference (bottom).  
48 The first two panels of the figure are an equivalent plot of Figure 3a-b.

49

50 Figure S6: Composite standard deviation of low frequency (90-years low pass filtered using  
51 Lanczos filter) annual SST (in °C) for (a) Type-1 and (b) Type-2 ENSO models from historical  
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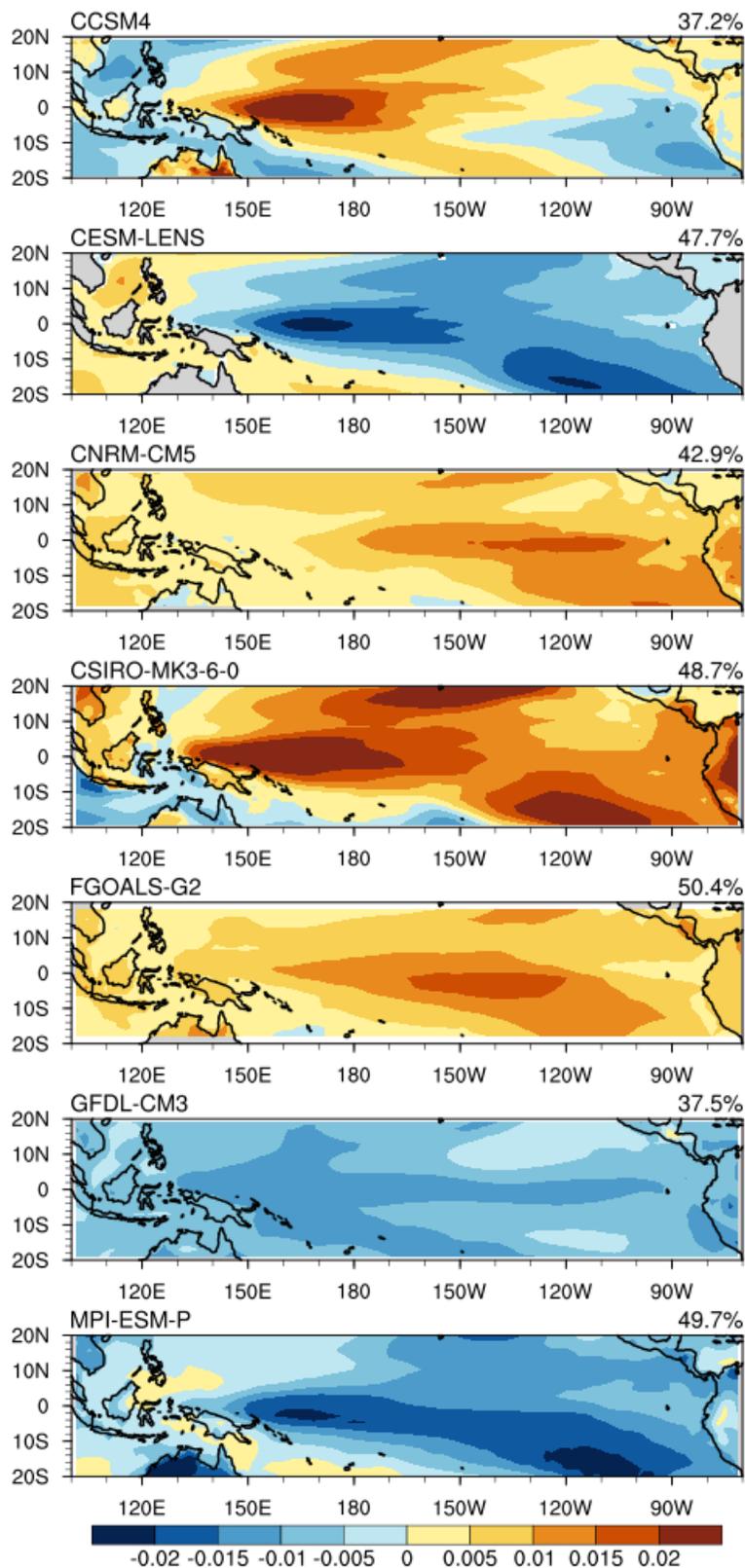
55 Figure S7: Observational equivalent of Figure 3. Standard deviation of (a) high-frequency (10-  
56 years high pass filtered using Lanczos filter) annual u10 (in m/s), and (b) low-frequency (90-years  
57 low pass filtered using Lanczos filter) annual SST (in °C). The u10 and SST are used from NOAA  
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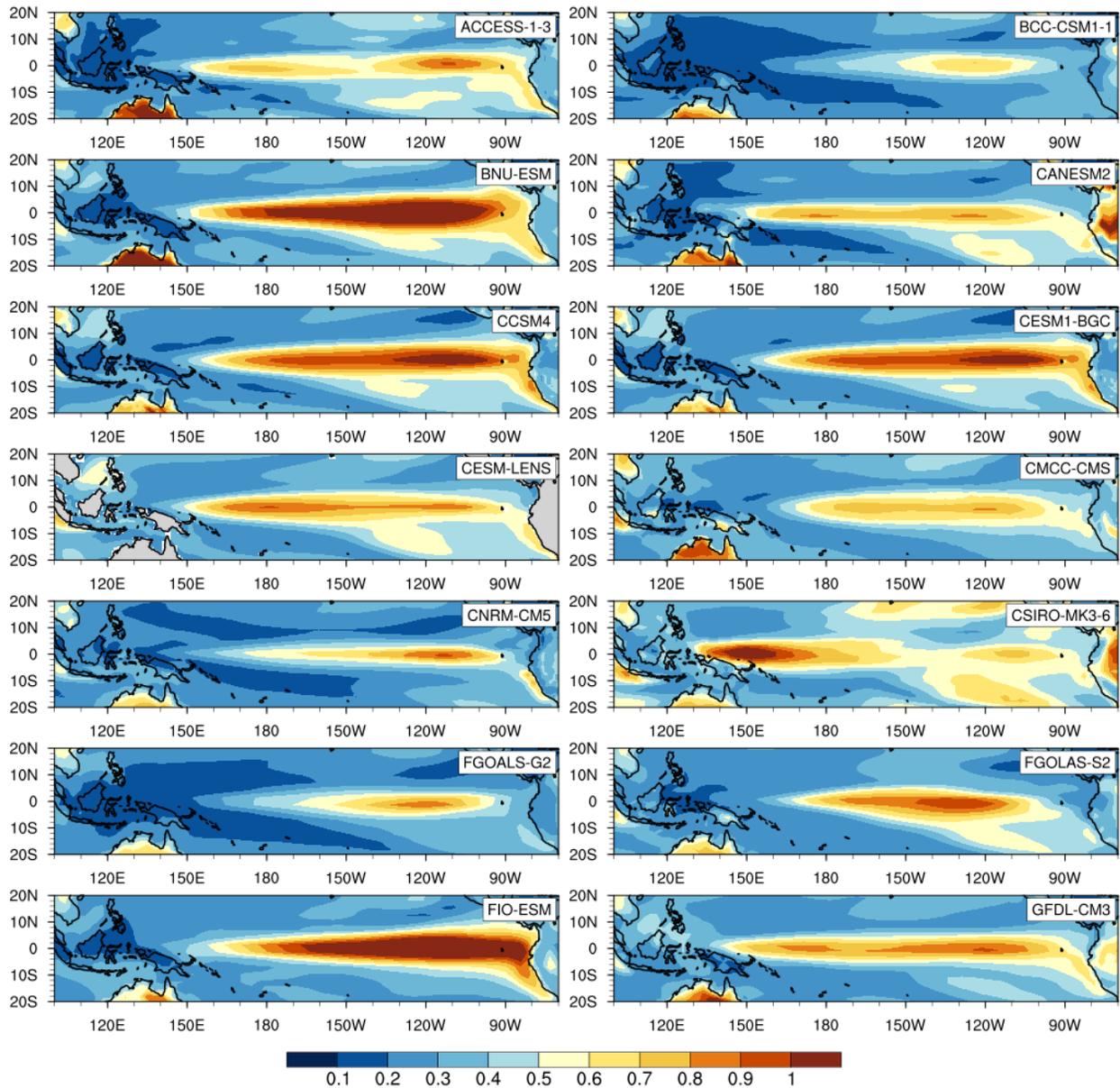
<b>Type-1 Model</b>	<b>Institute</b>	<b>Ocean</b>	<b>Atmosphere</b>	<b>Years</b>	<b>Reference</b>
CESM LENS	NCAR, USA	1.0 × 1.0	1.0 × 1.0	1801	Kay et al. (2015)
BNU-ESM	BNU, China	1.0 × 1.0	2.8 × 2.8	559	Xin et al. (2012)
CanESM2	CCCMA, Canada	1.4 × 0.9	2.8 × 2.8	996	Arora et al. (2011)
CCSM4	NCAR, USA	1.1 × 0.6	1.2 × 0.9	501	Gent et al. (2011)
CSIRO-MK3-6-0	CSIRO-QCCCE, Australia	1.9 × 0.9	1.9 × 1.9	500	Rotstayn et al. (2012)
GFDL-CM3	NOAA-GFDL, USA	1.0 × 1.0	2.5 × 2.0	500	Donner et al. (2011)
GFDL-ESM-2M	NOAA-GFDL, USA	1.0 × 1.0	2.5 × 2.0	500	Donner et al. (2011)
MPI-ESM-LR	MPI-N, Germany	1.5 × 1.5	1.9 × 1.9	1000	Roddatz et al. (2007)
MPI-ESM-P	MPI-N, Germany	1.5 × 1.5	1.9 × 1.9	1156	Roddatz et al. (2007)
<b>Type-2 Model</b>	<b>Institute</b>	<b>Ocean</b>	<b>Atmosphere</b>	<b>Years</b>	<b>Reference</b>
ACCESS1-3	CSIRO, Australia	1.0 × 1.0	1.9 × 1.2	500	Bi et al. (2013)
BCC-CSM-1-1	BCC, CMA, China	1.0 × 1.0	2.8 × 2.8	500	Xin et al. (2012)
CESM1-BGC	NCAR, USA	1.1 × 0.6	1.2 × 0.9	500	Long et al. (2012)
CMCC-CMS	CMCC, Italy	2.0 × 2.0	1.9 × 1.9	500	Scoccimarro et al. (2011)
CNRM-CM5	CNRM-CERFACS, France	1.0 × 0.8	1.4 × 1.4	850	Voldoire et al. (2013)
FGOALS-G2	LASG-CESS, China	1.0 × 1.0	2.8 × 2.8	700	Yongqiang et al. (2004)
FGOALS-S2	LASG-IAP, China	1.0 × 1.0	2.8 × 1.7	501	Yongqiang et al. (2004)
FIO-ESM	FIO, SOA, China	1.0 × 0.6	2.8 × 2.8	800	Yongqiang et al. (2004)
GFDL-ESM-2G	NOAA-GFDL, USA	1.0 × 1.0	2.5 × 2.0	500	Donner et al. (2011)
GISS-E2-H	NASA/GISS, USA	1.0 × 1.0	2.5 × 2.0	531	Schmidt et al. (2006)
GISS-E2-R	NASA/GISS, USA	1.2 × 1.0	2.5 × 2.0	550	Schmidt et al. (2006)
HADGEM2-AO	NIMR-KMA, Korea	1.0 × 1.5	1.9 × 1.2	700	Matin et al. (2011)
IPSL-CM5A-LR	IPSL, France	2.0 × 1.9	3.7 × 1.9	1000	Dufresne et al. (2013)
INMCM4	INM, Russia	0.8 × 0.4	2.0 × 1.5	500	Volodin et al. (2010)
MIROC-ESM	AORI-NIES-JAMSTEC, Japan	1.4 × 0.9	2.8 × 2.8	531	Watanabe et al. (2011)
MPI-ESM-MR	MPI-N, Germany	0.4 × 0.4	1.9 × 1.9	1000	Raddatz et al. (2007)
MRI-CGCM3	MRI, Japan	1.0 × 0.5	1.1 × 1.1	500	Yukumoto et al. (2012)
NorESM1-M	NCC, Norway	1.1 × 0.6	2.5 × 1.9	500	Bentsen et al. (2013)

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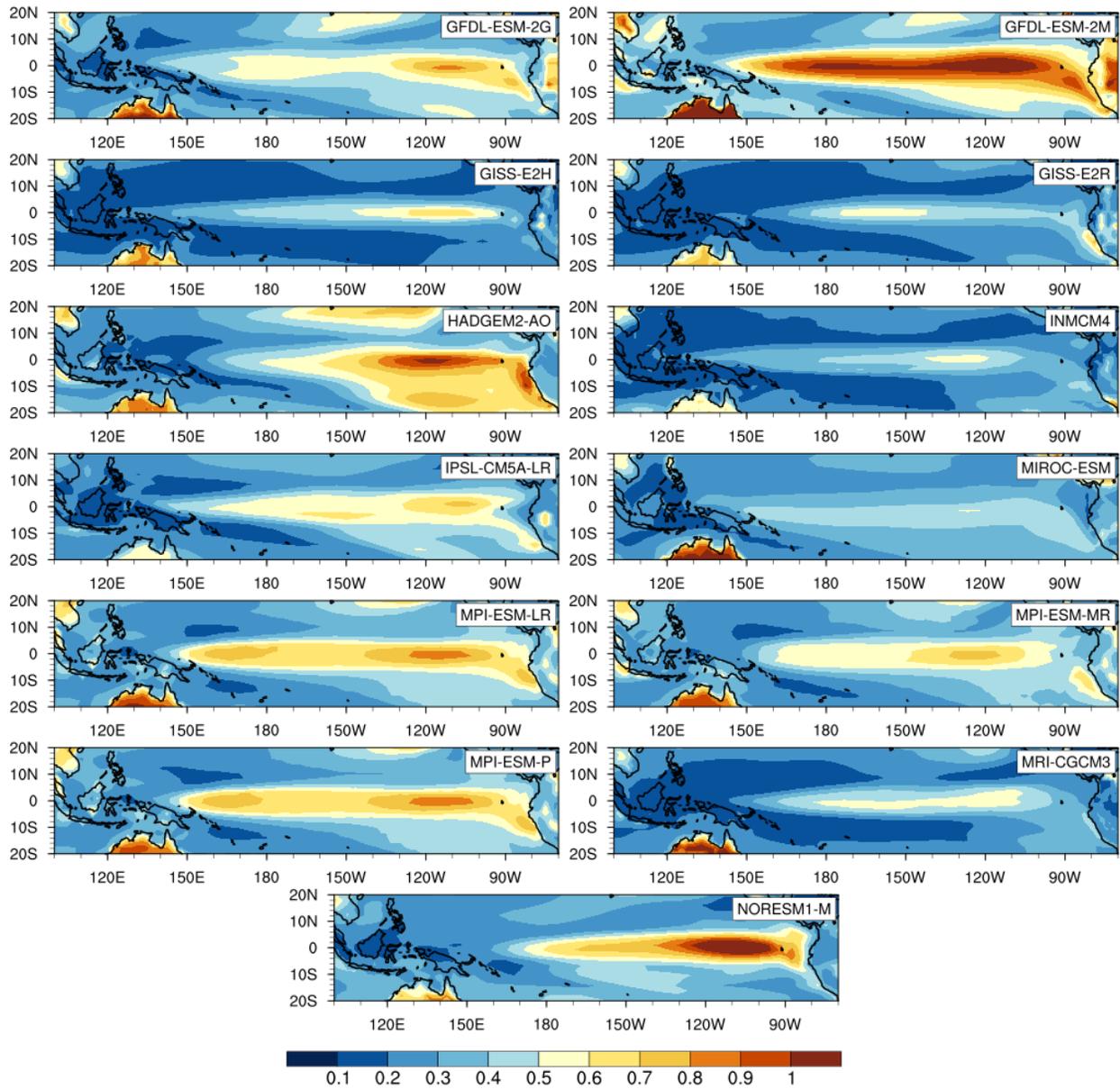


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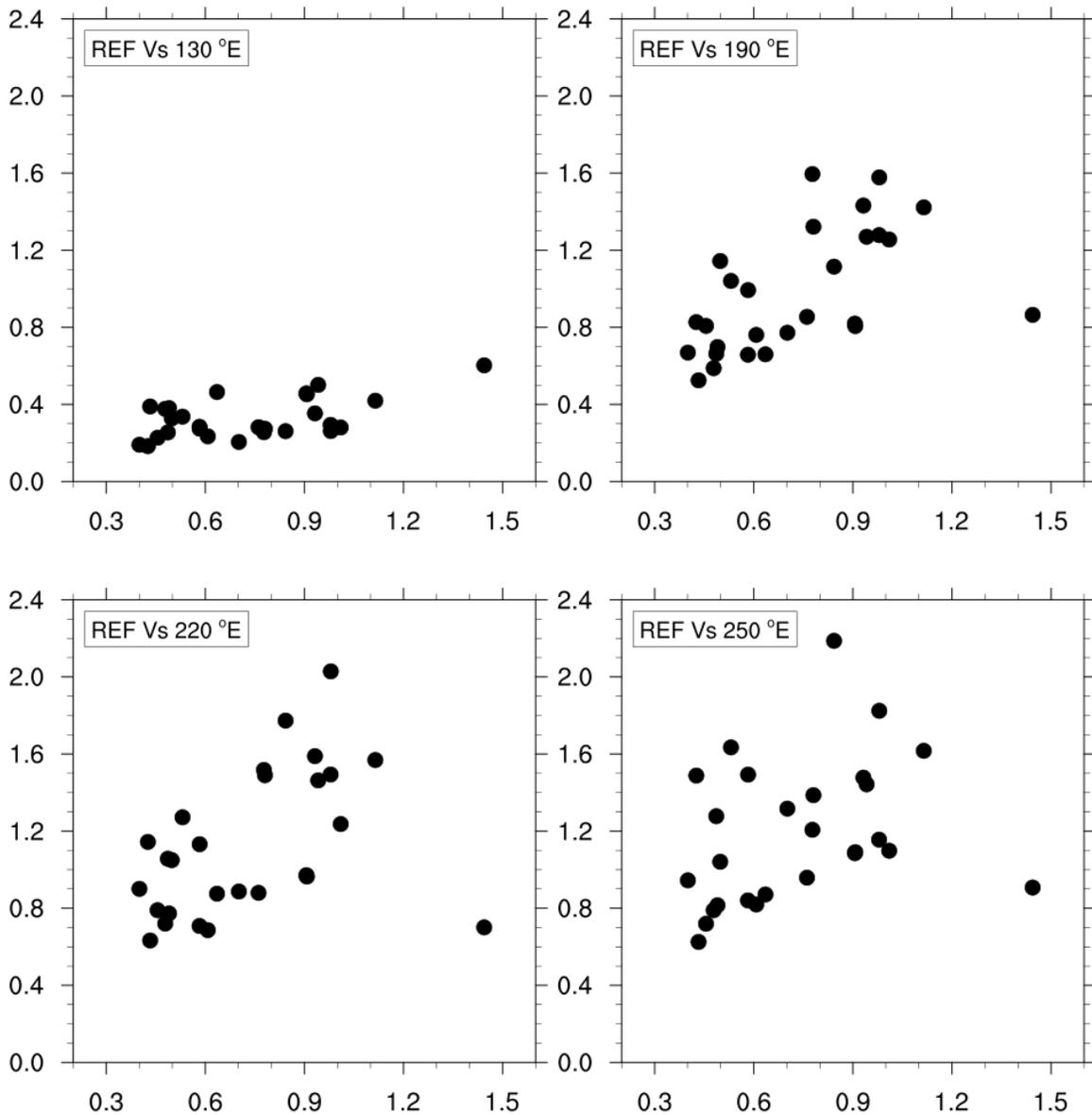
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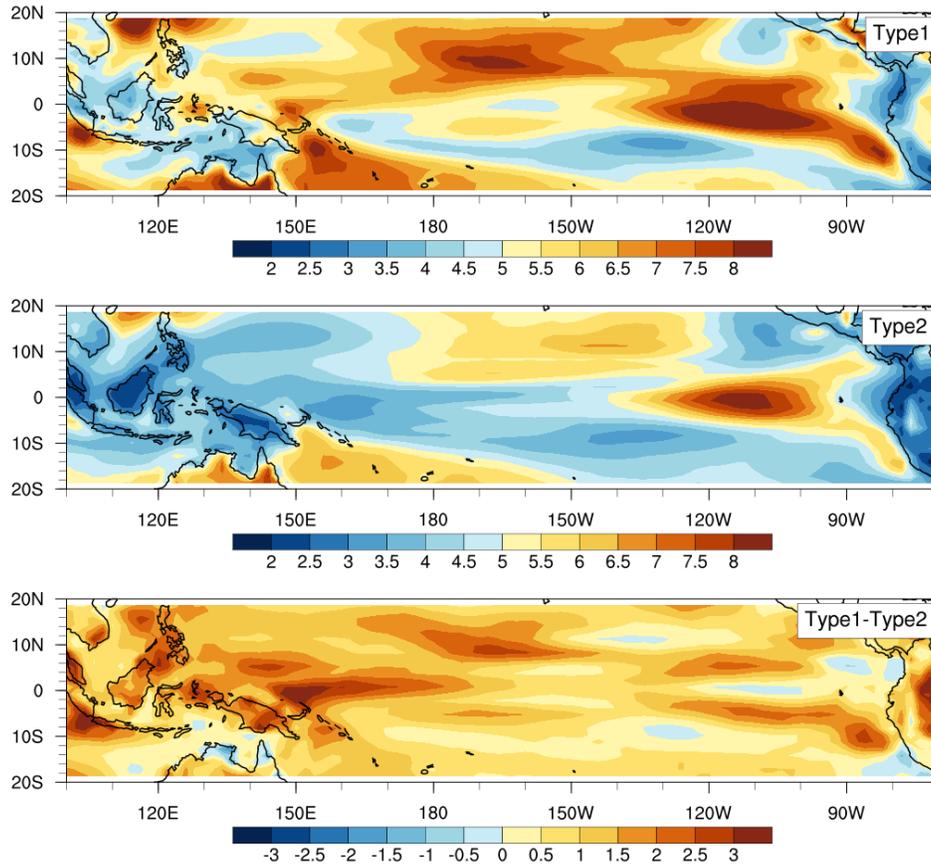
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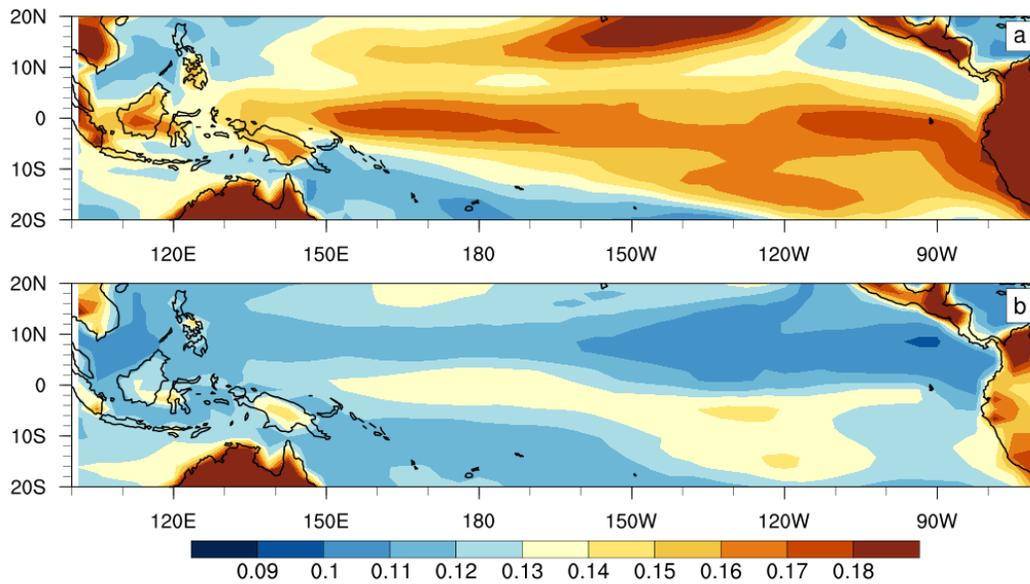
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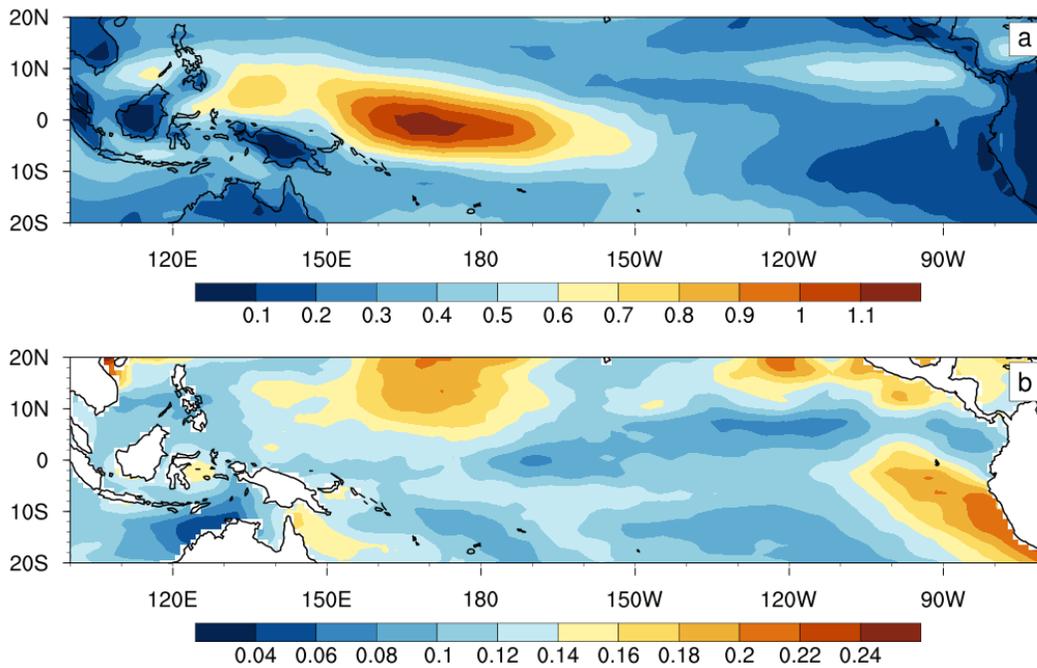


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## 117 Derivation of the analytical spectrum of the Hasselmann model

118 Hasselmann equation can be formulated as follows

$$119 \quad M \frac{dT(t)}{dt} = LT(t) + F(t) \quad (2)$$

120 where  $M = \rho C_p H$ ,

121  $\rho$  is the density of seawater,  $C_p$  is the specific heat capacity of seawater, and  $H$  is mixed layer  
122 depth.

123 Here the units of  $M$  is  $J/(m^2K)$ ,  $\frac{dT(t)}{dt}$  is  $K/s$ ,  $L$  is  $J/(m^2sK)$ ,  $T(t)$  is  $K$  and  $F(t)$  is  $J/(m^2s)$ .

$$124 \quad \text{This can be rewritten, } \frac{dT(t)}{dt} = \frac{-L}{M} T(t) + \frac{F(t)}{M}$$

125 And multiplying by  $e^{-i2\pi f t}$  and taking integral from  $\int_{-\infty}^{+\infty} dt$  gives

$$126 \quad \frac{dT(f)}{dt} = \frac{-L}{M} T(f) + \frac{F(f)}{M} \text{ where } T(f) = \int_{-\infty}^{+\infty} e^{-i2\pi f t} T(t) dt \text{ and } F(f) \text{ has an analogous form.}$$

127 Taking the derivative on the left-hand side of the equation gives

$$128 \quad -i2\pi f T(f) = \frac{-L}{M} T(f) + \frac{F(f)}{M}$$

$$129 \quad \text{Or, } T(f) \left( -i2\pi f + \frac{L}{M} \right) = \frac{F(f)}{M}$$

$$130 \quad \text{Or, } T(f) = \frac{F(f)}{(-i2\pi f M + L)}$$

131 Now, using that power spectral density is  $PSD(f) = \langle T^*(f)T(f) \rangle$ , the analytical power  
132 spectral density of the Hasselmann model is

$$133 \quad PSD(f) = \frac{\langle F^*(f)F(f) \rangle}{(i2\pi f M + L)(-i2\pi f M + L)} = \frac{\langle F^*(f)F(f) \rangle}{(2\pi f M)^2 + L^2} \quad (3)$$

134 where  $\langle F^*(f)F(f) \rangle$  is the power spectral density of the input noise forcing.

135

## 136 Derivation of the analytical spectrum of the white noise forcing that is the input noise forcing to 137 the Hasselmann model

138 Using the definition of the Autocorrelation function (ACF) of  $F(t)$

$$139 \quad ACF(F(t)) = \int_{-\infty}^{+\infty} F(t) \cdot F(t + \tau) d\tau; \text{ where } \tau \text{ is the lag} \quad (4)$$

140 And because  $F(t)$  is stationary Gaussian white noise

$$141 \quad ACF(F(t)) = \sigma^2 \delta(\tau) \quad (5)$$

142 Now, for continuous time, using the Wiener-Khinchin theorem, with the autocorrelation function  
143 defined in terms of statistical expected value (as  $F(t)$  is stationary). As the process is real valued,  
144 the power spectral density of  $F(t)$  is

$$145 \quad \int_{-\infty}^{+\infty} ACF(F(t)) e^{-i2\pi f \tau} d\tau \quad (6)$$

146 Now, from (5) and (6), the power spectral density of  $F(t)$  is then

147  $PSD(f) = \sigma^2 \int_{-\infty}^{+\infty} \delta(\tau) e^{-i2\pi f\tau} d\tau = \sigma^2$  (7)

148 Combining equations (3) and (7), the analytical spectrum of the Hasselmann model is thus, where  
149  $\sigma^2$  is the variance of the input noise forcing

150  $PSD(f) = \frac{\sigma^2}{(2\pi fM)^2 + \lambda^2}$