

1 **Auxiliary Material**

2 **Supplements 1-4**

3 **Klein et al.; 2013GC004858**

4
5 **Supplement 1: Evaluating the validity of photograph-based relative age scale with**
6 **U-Th radiometric age measurements.**

7 To evaluate the validity of our relative age scale, we draw upon data from a portion of the
8 EPR north of our study area where absolute lava ages have been measured
9 radiometrically and where the seafloor was photographed during lava collection. *Sims et*
10 *al.* [2002, 2003] report U-Th radiometric ages for lavas collected using DSRV Alvin
11 submersible on- and off-axis along the EPR at 9°48–52’N. Based on a comparison of the
12 radiometric ages and ages calculated on the basis of spreading rate (distance off-axis),
13 they concluded that a large number of off-axis samples were anomalous in that they had
14 erupted more recently than one would predict based on distance off-axis. However, at
15 least three off-axis samples had radiometric ages consistent with their spreading rate age.
16 These three samples, combined with two axial samples from the same study, were used to
17 explore the validity of our relative age scale and estimate absolute age based on seafloor
18 photographs.

19
20 Using archived photographs of seafloor near where each of the five samples was
21 collected (Figure A1; *D. Fornari, pers. comm.*), we assigned a relative age rank to each,
22 and compared these to radiometric ages [*Sims et al.*, 2003] reported for the five samples.
23 Strong linear correlations are found between our relative ages and U-Th trendline ages
24 (Figure A2). Similarly strong correlations are found between spreading rate age and both
25 relative age and radiometric age.

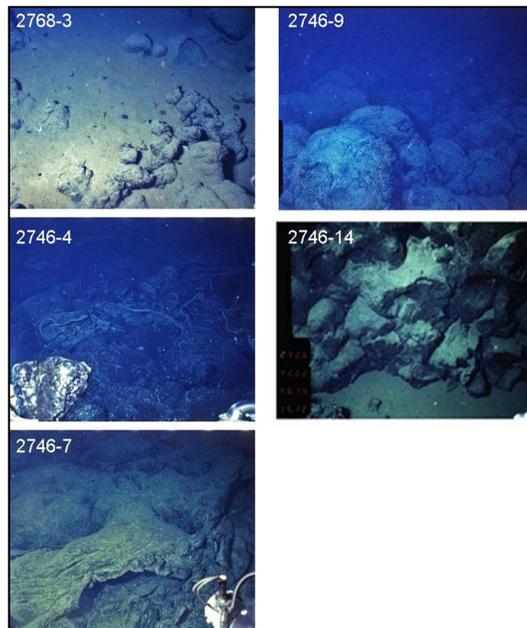
26
27 For the data of *Sims et al.* [2003], linear regression suggests that each unit increase in our
28 relative age rank represents an increase of ~18,000 years in absolute age. Importantly,
29 however, for the 9°50’N samples, as well for samples reported by Waters et al. [2013a,b]
30 our photographic estimates of ages for young seafloor (relative age ranks 1 or 2) appear

31 to less accurate; as shown in Figure A2, for example, seafloor with relative age ranks 1
32 and 2 have lavas with U-Th trendline ages reported as zero.

33

34 While the strong correlation between relative age rank and radiometric age supports the
35 use of photographic age estimates, the applicability of this relative age-radiometric age
36 calibration to other areas should be approached with caution because the visual
37 characteristics of the seafloor will be subject to local variables, such as sedimentation rate,
38 differences in lava morphology, terrain slope (affecting sediment thickness), tectonism
39 (affecting outcrop integrity), or hydrothermal circulation (affecting weathering rate).

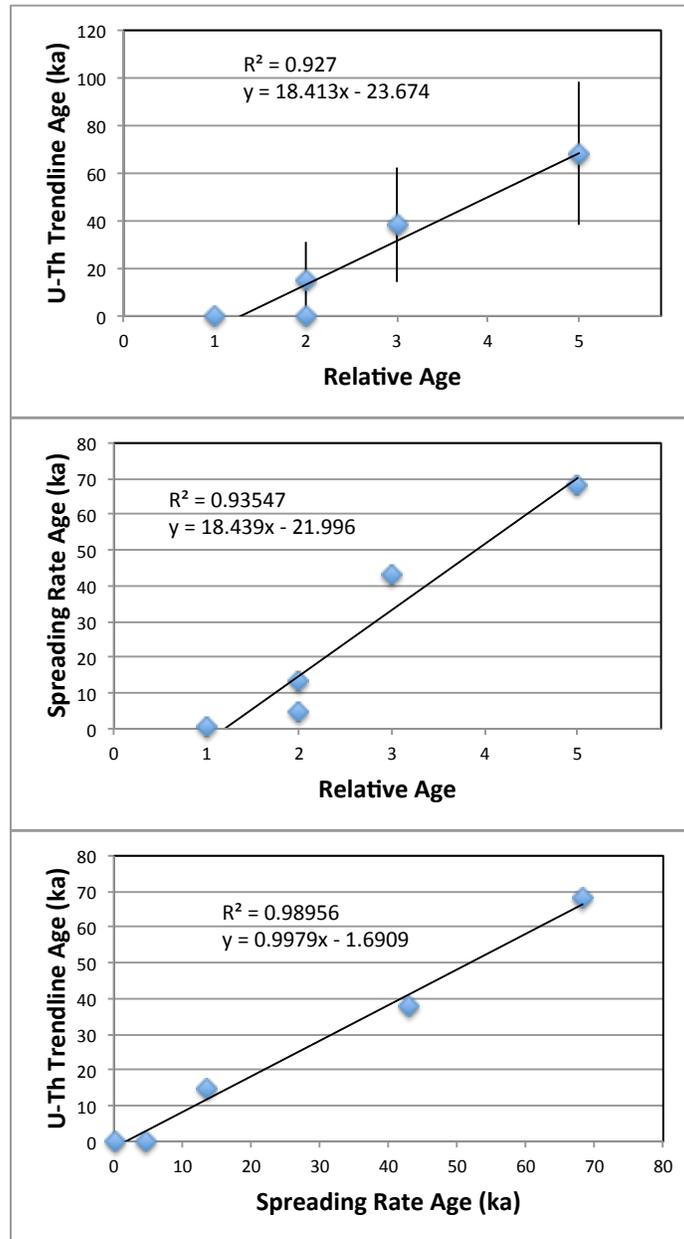
40



41

42 **Figure S1.** Photographs of seafloor near where samples were collected in the study of
43 the 9°50' N EPR region reported by *Sims et al.* [2003], with additional photographs
44 provided by D. Fornari (*pers. comm.*) These photographs were used to classify the
45 seafloor shown using our relative age scale. The relative ages were then compared to
46 ages estimated on the basis of spreading rate and absolute ages based on U-Th dating (see
47 Figure S2).

48



49

50 **Figure S2.** Age data for samples recovered on- and off-axis along the EPR at 9°48–52'N.

51 The five samples shown were judged by *Sims et al.* [2002, 2003] to be not anomalously

52 young, in contrast to other off-axis samples in their study. The three plots show the

53 correlations among relative ages (determined using our relative age scale), spreading rate

54 ages, and U-Th trendline ages [*Sims et al.*, 2003].

55

56 **Supplement 2: Bathymetry and digitizing seafloor geologic features**

57

58 Two existing data sets from this area were merged to create the bathymetry used in this
59 study. *White et al.* [2006] collected a Simrad EM300 bathymetry swath through the area
60 that was gridded at 30m x 30m, and *Combiier et al.* [2008] used seafloor reflections from
61 the ARAD seismic survey to create a 25m x 100m bathymetry grid. We resampled the
62 *Combiier et al.* grid using cubic convolution to match the EM300 grid, then overlaid the
63 EM300 data values, and clipped the grid to match the boundaries of the DSL-120a
64 backscatter mosaic. To eliminate sharp depth changes due to slight mismatches at the
65 boundary between bathymetric datasets, we used a weighted average of the values within
66 stripes running along the outer 400m (10%) of the EM300 swath. The grid values were
67 averaged using a weight assigned to each dataset as a linear function of distance to the
68 edge of the EM300 swath from 50% to each dataset at the edge to 100% EM300 at 400m
69 inside.

70

71 This bathymetric grid was median filtered using a 2 km² moving window, and then
72 subtracted from the original grid removing relief associated with the axial highs and
73 basin, to create a grid of local relief. From the local relief grid we derived several
74 topographic metrics: the mean of aspect in 500 m circular neighborhoods; range of local
75 relief in 500 m circular neighborhoods; standard deviation of surface roughness in 700 m
76 by 400 m neighborhoods; and mean of slope in 500 m circular neighborhoods.

77

78 Mounds, fissures and faults observed in backscatter images were identified and digitized
79 as follows (Figure 7). The base of the mounds was found by viewing bathymetry
80 simultaneously with backscatter. Closed contours (5m interval) were used to initially
81 identify a mound and the base was digitized from a break in slope on the backscatter and
82 bathymetry to retain the highest resolution possible. Fissures and faults were manually
83 digitized by tracing the length of a paired bright-dark backscatter reflection in the case of
84 fissures, or a single linear reflector coinciding with a bathymetric gradient for faults.

85

86 **Supplement 3: Supervised and Unsupervised Automated Seafloor Classification**

87

88 Supervised and unsupervised classifications were both used for this study in order to
89 compare the supervised result based on predetermined, user-defined classes to the
90 unsupervised result based on user-independent clustering of data values. Unlike typical
91 supervised classifications, no definitive dataset describing different seafloor terrains
92 exists for training the classifier. *Sempere and Macdonald* [1986a] provide the closest
93 approximation to prior definitions by identifying OSC provinces, and so we adapted their
94 provinces to train the supervised classifier. By comparing results from the supervised and
95 unsupervised classifications on the same data, we can determine the extent to which our
96 choice of training data has influenced the outcome (Figure 8a,b).

97

98 Unsupervised classifications receive no *a priori* information about what classes exist. In
99 an unsupervised classification, the computer uses an algorithm, in our case the ISODATA
100 clustering algorithm, that examines the raster stack and classifies the cells that meet
101 criteria for similarity into the same class [*Jensen, 2005*]. The user specifies the number
102 of classes that should be contained in the output, and classification runs until a
103 convergence threshold or the maximum number of iterations has been reached. Several
104 unsupervised classifications were run, with different numbers of classes specified at
105 input, to determine the spatial pattern and number of classes that appeared consistently.

106

107 We initially selected an 11-class output from the unsupervised classification, which
108 produced incoherent patterns of mixed pixel values within larger blocks of only a few
109 classes. As the number of classes was reduced, larger blocks of pixels consisting of the
110 same value appeared. When these classes were combined, large areas containing only
111 one class were generated, and we used these as the final result for comparison to the
112 classes produced from the supervised classification. The unsupervised classification of
113 texture and residual bathymetry produced only four classes (Figure 8b).

114

115 A supervised classification uses specified data (e.g., terrain areas) chosen by a user to
116 describe a particular signature, to train the computer to classify on the basis of the

117 different characteristics. The computer then uses these characteristics to assign terrain
118 classes to every pixel in the study area, based on seafloor texture from side-scan, and
119 seafloor relief, slope and aspect from bathymetry in our case, to identify other seafloor
120 areas with matching characteristics. Areas of interest (AOIs) are polygons created
121 manually that only contain points representing a single class based on *a priori*
122 understanding of the classes that the user wants the classifier to find. We created five
123 AOIs derived from the five provinces defined by *Sempere and Macdonald* [1986a] for
124 the supervised classification. AOIs were drawn approximately centered within and to
125 half the total length and width of the provinces in *Sempere and Macdonald* [1986a].
126 Maximum likelihood calculates the probability that a cell belongs to each class from
127 maximum likelihood probability statistics and assigns the cell to the class with the
128 highest probability.

129

130 The supervised classification also found four specific provinces (Figure 8a), despite the
131 fact that the classifier was trained on five different AOIs, corresponding to the five
132 provinces of *Sempere and Macdonald* [1986a]. This illustrates the fact that tectonically
133 defined provinces may contain a mixture of distinct seafloor terrains (see, for example,
134 the complex mix of terrains found in the tectonically defined “eastern ridge tip.” Names
135 for each province were chosen based on the gross morphologic characteristic of each
136 province: Smooth, Hummocky, Fissured, and Mounded provinces.

137 To produce the final terrain classification maps (Figure 8), we applied a boxcar mode
138 filter over a 7x7 cell (210 x 210 m) area. This removed isolated individual or small
139 groups of pixels from within larger areas of a different class. Two iterations of this filter
140 were applied. The border of the final map was trimmed by one filter width (210 m) to
141 eliminate edge effects due to the window size applied during data processing.

142

143 **Supplement 4: Accuracy Assessment of terrain classification**

144 In order to assess the internal consistency of the supervised classification method, an
145 accuracy assessment was performed by comparing the output cell values from the
146 classifier within each AOI to the value we assigned to that AOI. The AOIs were chosen

147 somewhat *ad hoc* from the areas picked by *Sempere and Macdonald* [1986a] to define a
148 supposedly uniform terrain signature. It was unclear at the outset if these AOIs would be
149 appropriately distinctive; by comparison, traditional training data for a supervised
150 classification generally represent well-agreed-upon categorical features (e.g. streets,
151 buildings, forests). The purpose of this accuracy assessment is to determine to what
152 extent each AOI contains a unique terrain signature. If the AOI represents a unique and
153 distinct terrain province, then the classifier should reproduce the uniform value of the
154 cells chosen by the user for that AOI. Unlike traditional accuracy assessments, it does not
155 provide an estimate of the accuracy of the classification of regions outside of AOI.

156 To perform the accuracy assessment, we used the direct output from the supervised
157 classifier before the mode filter smoothing was applied. User's and producer's errors
158 were calculated from the class chosen automatically by the supervised classifier and our
159 pre-assigned AOI class (Table D1). The Kappa coefficient uses the number of cells
160 classified correctly within each AOI and the total number of cells classified that represent
161 a specific province that are found over the entire classified image. Kappa value of 0.79
162 was obtained for the supervised classifications, which falls at the boundary between
163 "strong" and "very good" agreement between the predefined areas and the classifier
164 output (*Jensen, 2005*). The result indicates that the classifier consistently reproduces the
165 classes chosen to represent distinct terrains in four out of five areas, with the fifth area
166 being consistently identified as one of the other four.

167

168 The high Kappa value and close correspondence between the supervised and
169 unsupervised classifications indicates the four provinces are robust representations of the
170 local terrain types on a landscape scale. The precision of the boundaries of the provinces
171 is a function of the size of the analysis window, which is 1 x 2 km in this study. A
172 kilometer level of precision seems appropriate for this study since the tectonic and
173 magmatic processes attributed to creating these provinces are such that transitions would
174 be likely to occur on a similar scale.

175

Province Cells	Basin AOI	East Limb Tip AOI	West Limb AOI	West Limb Tip AOI	East Limb AOI	<i>TOTAL</i>
Basin	48325	0	15	1609	1	49950
East Limb Tip	-	-	-	-	-	0
West Limb	0	36797	56906	1530	288	95521
West Limb Tip	171	6169	1143	68973	6154	82610
East Limb	2	173	0	1600	122851	124626
<i>TOTAL</i>	48498	43139	58064	73712	129294	352707

176 **Table S1.** Contingency table created using the output from the supervised terrain
177 classification (rows) and the user-defined areas of interest (AOI) (columns).